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Continuation

DROP : Steady drop and film states on a horizontal homogeneous substrate

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1 drop : Steady drop and film states on a horizontal homogeneous substrate

The tutorial DROP explores an equation for steady drop-and-hole solutions derived from the dimensionless thin film (or lubrication) equation. You will calculate steady solution of the equation by continuation in a number of different control parameters (domain size, mean height).

1.1 Model

This demo illustrates the calculation of steady drop and hole solutions of the dimensionless thin film (or long-wave) equation

$$\partial_t h = -\partial_x \{Q(h) \partial_x [\partial_{xx} h - \partial_h f(h)]\} \quad (1.1)$$

where $Q(h) = h^3$ is the mobility factor (not relevant for steady states). For background information see [1, 2, 3, 4]. The term in square brackets represents the negative of a pressure that consists of the Laplace (or curvature) pressure $-\partial_{xx} h$ and an additional contribution $\partial_h f(h)$ written as the derivative of a local free energy $f(h)$. The Laplace pressure is the pressure difference across a curved interface caused by its surface tension. If R_1 and R_2 are the principal radii of curvature the pressure jump is proportional to $\frac{1}{R_1} + \frac{1}{R_2}$. Here, only the curvature of the free surface of the drop gives a contribution, which is in long-wave approximation approximately the second spacial derivative of the height profile.

The local free energy has a particular form for each studied problem. For specific examples see [5, 6, 7, 8, 9, 10]. In the demo we use a simple Derjaguin (or disjoining/conjoining) pressure $\Pi(h) = -\partial_h f(h)$ that describes wettability for a partially wetting liquid (see reviews [11, 12, 13]). In particular, we employ a combination of two inverse power laws in h [7, 14].

$$\partial_h f(h) = -\Pi(h) = \frac{1}{h^3} - \frac{1}{h^6}. \quad (1.2)$$

To study steady solutions, i.e., resting droplets or films, we set $\partial_t h = 0$ and integrate Eq. (1.1) twice (this is possible as the first integration constant, the flux C_0 , is zero for systems without through-flow [3], then one may divide by $Q(h) \neq 0$ and the second time.

One obtains

$$0 = \partial_{xx} h(x) - \partial_h f(h) + C_1. \quad (1.3)$$

The constant C_1 accounts for external conditions like chemical potential, vapor pressure or mass conservation. Here we consider the latter case where C_1 takes the role of a Lagrange multiplier for mass conservation. To use the continuation toolbox auto07p [15], we first write (1.3) as a system of first-order autonomous ordinary differential equations on the interval $[0, 1]$. Therefore, we introduce the variables $u_1 = h - h_0$ and $u_2 = dh/dx$, and obtain from equation (1.3) the 2d dynamical system (NDIM = 2)

$$\begin{aligned} \dot{u}_1 &= L u_2 \\ \dot{u}_2 &= L [f'(h_0 + u_1) - C_1]. \end{aligned} \quad (1.4)$$

where L is the physical domain size, and dots and primes denote derivatives with respect to $\xi \equiv x/L$ and h , respectively. The advantage of the used form is that the fields $u_1(\xi)$ and $u_2(\xi)$

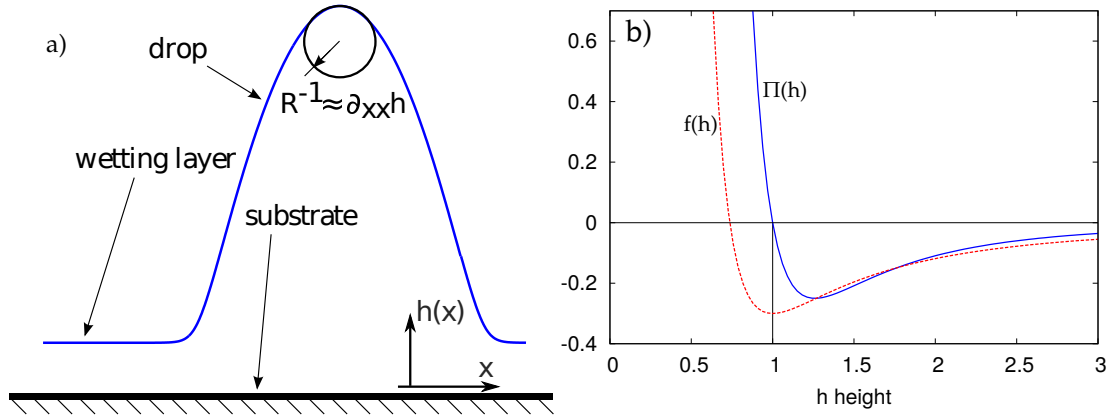


Figure 1.1: Panel (a) provides a sketch of the geometry employed in the demo drop. It shows a small droplet that coexists with an ultrathin wetting layer (precursor film) in a situation with laterally periodic boundary conditions, as introduced in Eq. (1.6). Note that the radius of curvature can be both positive and negative and competes with the Derjaguin pressure $\Pi(h)$. Panel (b) gives typical functional dependencies on h of the Derjaguin pressure and the local free energy $f(h)$.

correspond to the correctly scaled physical fields $h(L\xi)$ and $\partial_x h(L\xi)$. We use periodic boundary conditions for u_1 and u_2 (NBC = 2) that take the form

$$u_1(0) = u_1(1), \quad (1.5)$$

$$u_2(0) = u_2(1), \quad (1.6)$$

and integral conditions for mass conservation and computational pinning (to break the translational symmetry that the solutions have on the considered homogeneous substrate) (NINT = 2). The integral condition for mass conservation takes the form

$$\int_0^1 u_1 \, d\xi = 0. \quad (1.7)$$

As starting solution we use a small amplitude harmonic modulation of wavelength $L_c = 2\pi/k_c$ where $k_c = \sqrt{-f''(h_0)}$ is the critical wavenumber for the linear instability of a flat film of thickness h_0 . This results in $C_1 = f'(h_0)$ as starting value for C_1 .

The number of free (continuation) parameters is given by $\text{NCONT} = \text{NBC} + \text{NINT} - \text{NDIM} + 1$ and is here equal to 3.

There is a further complication as Eq. (1.3) corresponds to a conservative dynamical system (not a dissipative one). To deal with this we employ an 'unfolding parameter' ϵ that transforms the conservative in a 'virtual' dissipative system (with the same solutions). Different formulations are possible. Here we use:

$$\begin{aligned} \dot{u}_1 &= Lu_2 - \epsilon[f'(\bar{h} + u_1) - C_1] \\ \dot{u}_2 &= L[f'(\bar{h} + u_1) - C_1]. \end{aligned} \quad (1.8)$$

The technique is mentioned in the auto07p [15] demo 'r3b' and further explained in Refs. [16, 17, 18]. It corresponds to the introduction of an unfolding term that embeds the conservative system into a one-parameter family of dissipative systems. Thereby the unfolding parameter ϵ creates a one-parameter family of periodic solutions. Periodic solutions only exist for $\epsilon = 0$.

1.2 Runs:

Python interface command line	Terminal command line
<i>auto</i>	
<p>run 1: Determine steady solutions as a function of domain size L, starting at the critical L_c with a small amplitude sinusoidal solution. Mean thickness $h_0 = 3$ is fixed. One finds that the primary bifurcation is subcritical, and that the branch turns towards larger L at a saddle-node bifurcation at some $L_{sn} < L_c$. Compute the branch of periodic solutions for $h_0 = 3$ continued in L (PAR(5)) up to $L = 100$. Remaining true continuation parameters: C_1 (PAR(6)) and ϵ (PAR(2)); Other output: amplitude of h (PAR(7)), maximal slope of h. i.e., the mesoscopic contact angle θ_{mes} (PAR(46)) Parameter: IPS= 4, ISP= 0, ISW= 1, ICP= [5, 6, 2, 7, 46], Start data from function <i>stpnt</i> (IRS= 0) save output-files as <i>b.d1</i>, <i>s.d1</i>, <i>d.d1</i></p>	
<i>r1 = run(e = 'drop', c = 'drop.1', sv = 'd1')</i>	<i>@@R drop 1</i> <i>@sv d1</i>
<p>run 11: Restart at domain size $L = 100$, change mean thickness h_0. Continued in mean thickness h_0 (PAR(1)) for fixed domain size L. Stop at $h_0 = 10$ Remaining true continuation parameters: C_1 (PAR(6)) and ϵ (PAR(2)) Other output: as in run 1 Parameters: IPS= 4, ISP= 0, ISW= 1, ICP= [1, 6, 2, 7, 46], Start at final result of run 1: IRS= 7 save output-files as <i>b.d11</i>, <i>s.d11</i>, <i>d.d11</i></p>	
<i>r11 = run(r1, e = 'drop', c = 'drop.11', sv = 'd11')</i>	<i>@@R drop 11 d1</i> <i>@sv d11</i>
<p>run 2: Same as run 1 but continuing to large drops $L = 10^5$. save output-files as <i>b.d2</i>, <i>s.d2</i>, <i>d.d2</i></p>	
<i>r2 = run(e = 'drop', c = 'drop.2', sv = 'd2')</i>	<i>@@R drop 2</i> <i>@sv d2</i>
Plot the results.	
<i>plot('d1')</i> <i>plot('d11')</i> <i>plot('d2')</i>	<i>@pp d1</i> <i>@pp d11</i> <i>@pp d2</i>
<i>clean()</i>	<i>@cl</i>

Table 1.1: Commands for running demo drop.

1.3 Remarks:

- In thermodynamic context, the constant C_1 corresponds to the negative of the chemical potential.
- The *.f90 file provides another integral condition that is not used in the demo. If used it allows for a determination of the energy of the obtained steady state solutions.
- Beside the NCONT true continuation parameters that have to be given as ICP in the c.*

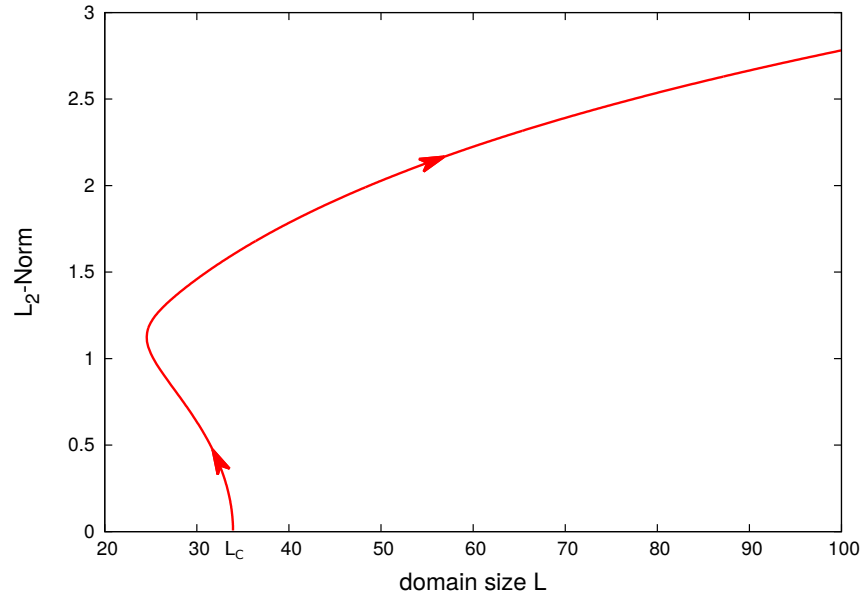


Figure 1.2: An illustration for run 1 of demo `drop` is given. The L_2 -norm of steady solutions is shown in dependence of the principal continuation parameter domain size L (`par(5)`) for mean film thickness $h_0 = 3.0$. The arrow indicates the direction of the path continuation.

parameter file, one may list other output parameters as defined in the subroutine PVLS in the *.f90 file.

- Screen output and command line commands are provided in README file.

1.4 Tasks:

After running the examples, you should try to implement your own adaptations, e.g.:

1. Redo run 1 for other values of h_0 , e.g., 1.27, 1.5, 2.5, 5.0, 10.0. What do you observe?
2. Redo run 11 allowing the code to go beyond $h_0 = 10$. What do you observe?
3. Try to run a continuation with fixed C_1 (you need to 'set free' another parameter). Compare your results with [4].
4. Activate the additional integral condition to measure the energy

$$E = \int_L \left(\frac{u_2^2}{2} + f(h) - f(h_0) \right) d\xi \quad (1.9)$$

of the solutions.

5. Replace the used Derjaguin pressure by a different one that you get from the literature. ([8], [19] or [5])

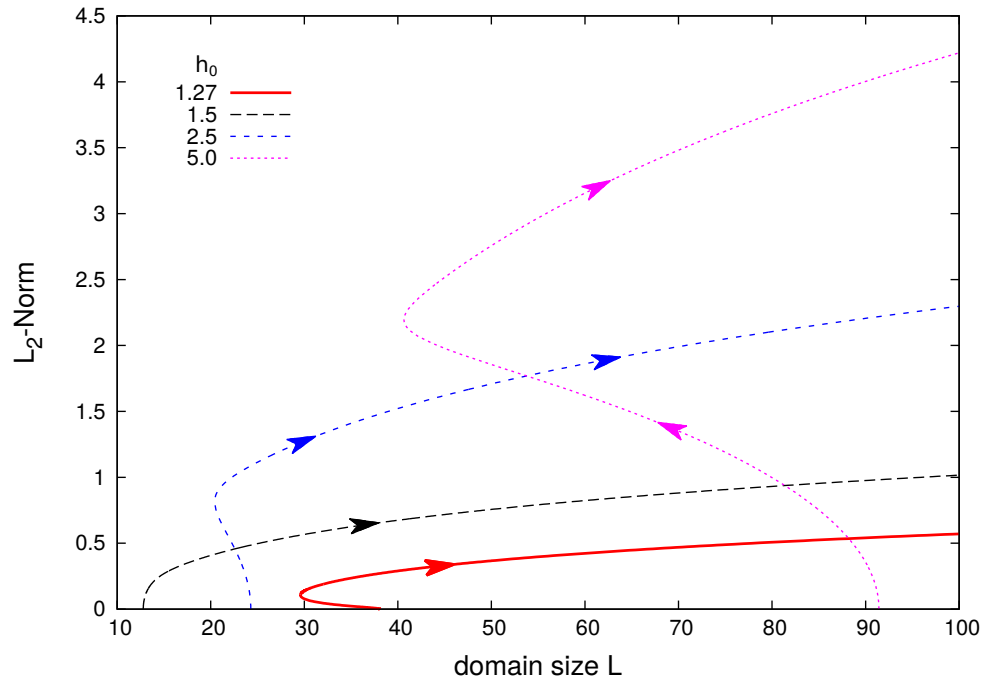


Figure 1.3: An illustration for task 1 of demo drop is given. The L_2 -norm of steady solutions is shown in dependence of the principal continuation parameter domain size L (par(5)) for various fixed mean film thicknesses as given in the legend.

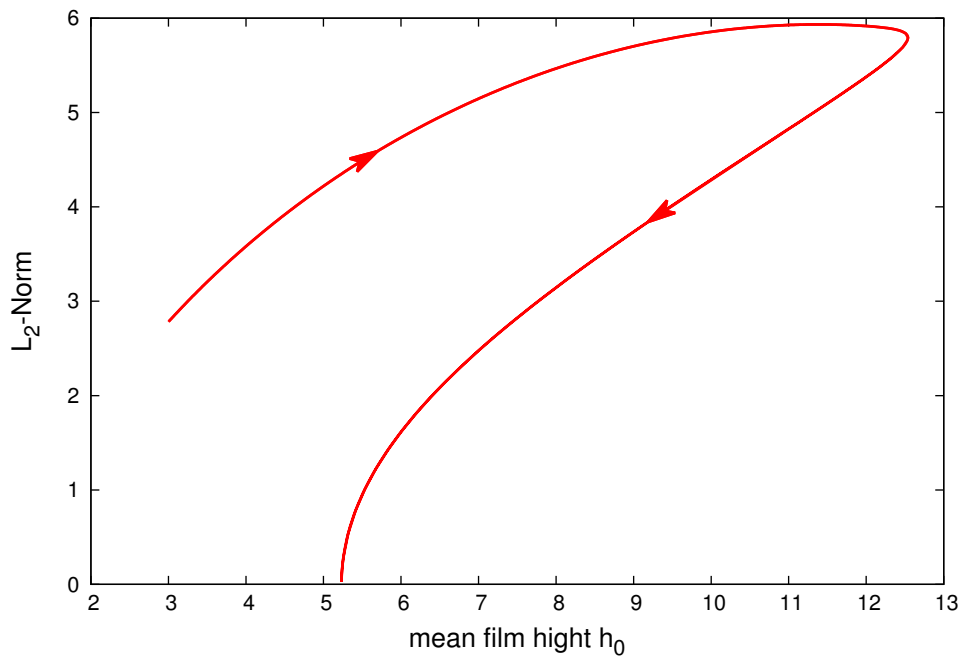


Figure 1.4: An illustration for task 2 of demo drop is given. The L_2 -norm of steady solutions is shown in dependence of the principal continuation parameter mean film height h_0 (par(1)) for fixed domain size $L = 100$. The drop size increases with h_0 up to $h_0 \approx 12.5$ where a saddle-node bifurcation occurs (the drop fills the entire domain). The lower branch corresponds to unstable hole (nucleation) solutions. The arrow indicates the direction of the path continuation.

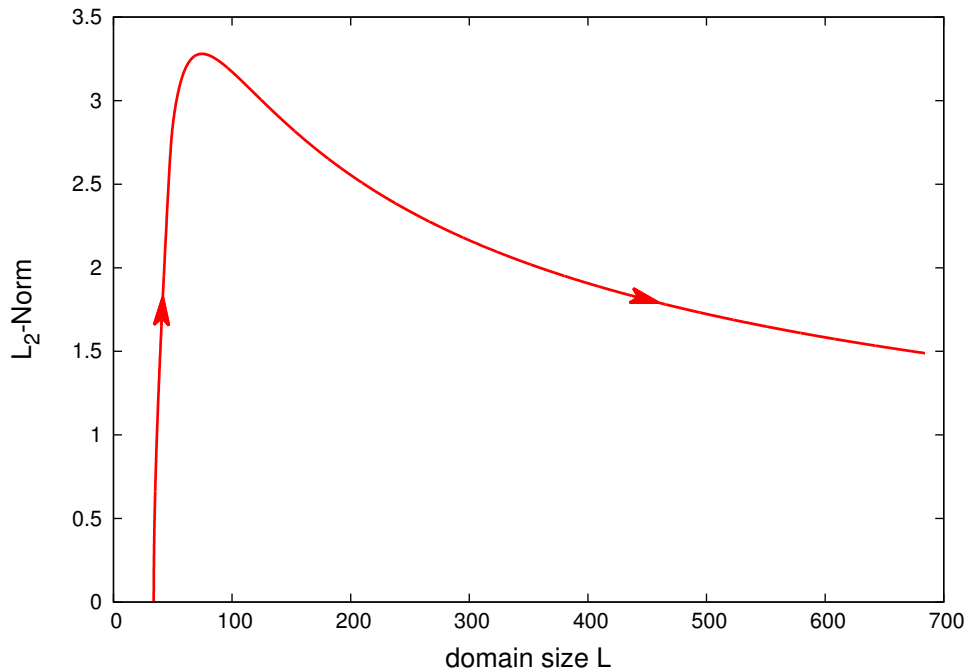


Figure 1.5: An illustration for task 3 of demo drop is given. The L_2 -norm of steady solutions is shown in dependence of the principal continuation domain size L (par(5)) for fixed chemical potential $C_1 = f(h = 0)$ (par(6)).

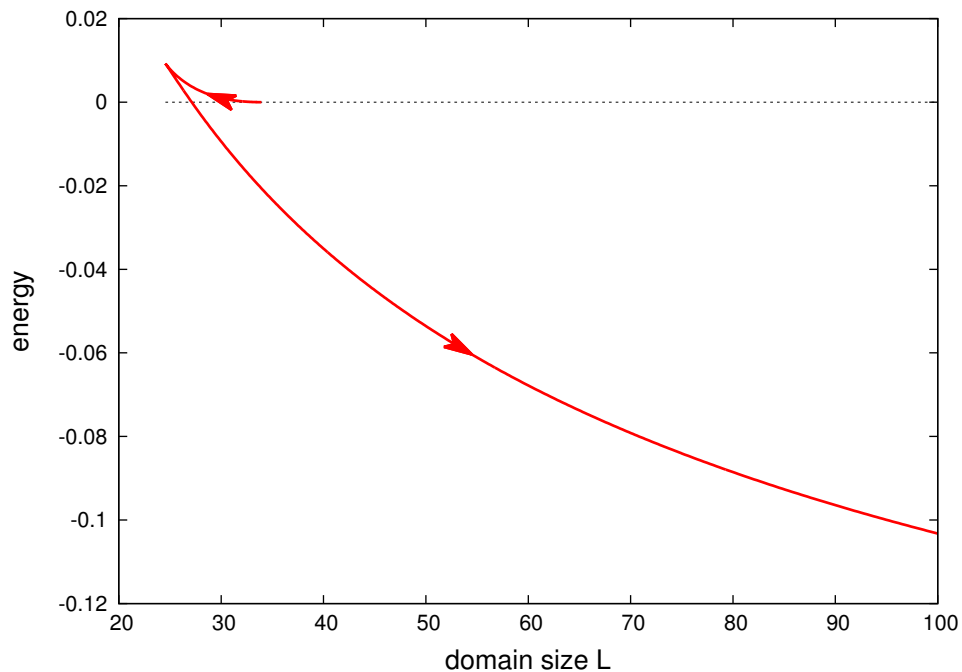


Figure 1.6: An illustration for task 4 of demo drop is given. The energy (1.9) of steady solutions is shown in dependence of the principal continuation parameter domain size L (par(5)) for fixed mean film thickness $h_o = 3.0$.

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