

# General Relativity and Black Holes – Week 1

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## 1 Exercises

1. Prove that a smooth manifold (as defined in lectures) has a countable atlas.
2. Let  $V$  be an  $n$ -dimensional real vector space. Prove that there exists a unique manifold structure (up to diffeomorphism) on  $V$  such that every linear isomorphism into  $\mathbb{R}^n$  is a coordinate chart.
3. Prove that the tangent space  $T_p M$  of an  $n$ -dimensional manifold  $M$  (as defined in lectures) is an  $n$ -dimensional vectorspace. Show also that tangent vectors satisfy the Leibniz product rule, i.e. if  $X_p \in T_p M$  and  $f, g \in C_p^\infty(M)$ , then

$$X_p(fg) = f(p)X_p(g) + X_p(f)g(p),$$

where the product of  $fg$  is defined by  $fg(p) = f(p)g(p)$ .

4. Let  $V$  be a vectorfield field on an  $n$ -dimensional manifold  $M$  and  $p$  a point such that  $V(p) \neq 0$ . Then there is a coordinate system  $x^1, x^2, \dots, x^n$  at  $p$  such that  $V = \frac{\partial}{\partial x^1}$  on this coordinate neighbourhood.
5. Let  $X, Y, Z$  be smooth vector fields on a manifold  $M$ . Additionally, let  $a$  and  $b$  be real numbers, and let  $f$  and  $g$  be smooth functions on  $M$ . Prove that the commutator (also called the Lie bracket) satisfies the following:
  - (a)  $[X, Y] = -[Y, X]$  (*anticommutativity*)
  - (b)  $[aX + bY, Z] = a[X, Z] + b[Y, Z]$  (*linearity*)
  - (c)  $[[X, Y], Z] + [[Y, Z], X] + [[Z, X], Y] = 0$  (*Jacobi identity*)
  - (d)  $[fX, gY] = fg[X, Y] + fX(g)Y - gY(f)X$

## 2 Problems and Discussion

We say that an open cover  $\mathcal{U}$  of a manifold  $M$  is *locally finite* if every point  $p \in M$  has a neighborhood which intersects (non-trivially) finitely many members of  $\mathcal{U}$ . Additionally, we say that an open cover  $\mathcal{V}$  is a *refinement* of  $\mathcal{U}$  if every member of  $\mathcal{V}$  is contained within a member of  $\mathcal{U}$ . Given an open cover  $\mathcal{U}$  of a manifold  $M$ , we define a *partition of unity* subordinate to  $\mathcal{U}$  to be a countable collection of smooth maps  $f_i : M \rightarrow [0, 1]$  such that

- There exists a locally finite refinement  $\mathcal{V}$  of  $\mathcal{U}$  such that  $\text{supp } f_i \subset V_i$  for some  $V_i \in \mathcal{V}$ .
- $\sum_i f_i(p) = 1$  for all  $p \in M$ .

We will generally take  $\mathcal{U}$  to consist of the domains of coordinate charts. Note that the first condition implies that, for  $p \in M$ , there exists a neighborhood of  $p$  in which  $f_i$  is identically zero for all but finitely many  $i$ .

1. (*Existence for partitions of unity*) Let  $\mathcal{U}$  be an open covering of a smooth manifold  $M$ . Show that there exists a locally finite open cover  $\{V_i\}$  such that the closure  $\bar{V}_i$  of each  $V_i$  is compact and contained in an element of  $\mathcal{U}$ . Consequently, there exists a partition of unity subordinate to  $\mathcal{U}$ 
  - (a) Show that the set of basis elements  $V_\beta$  which have compact closure, and which are subsets of both an element of  $\mathcal{U}$  and the domain of a coordinate chart, form a countable open cover.
  - (b) Construct a countable sequence of compact sets  $K_1, K_2, \dots$  such that  $K_i \subset \text{int } K_{i+1}$ ,  $\cup K_i = M$ , and each  $K_i$  is the union of finitely many  $\bar{V}_\beta$ .
  - (c) Use the construction of  $\{K_i\}$  to construct a locally finite open cover.
  - (d) Use this cover to construct a partition of unity.
2. (*Existence, uniqueness, and continuous dependence on initial data for ODEs*) Recall the following:  
Let  $x : \mathbb{R} \rightarrow \mathbb{R}^n$  satisfy the initial value problem

$$x'(t) = f(t, x), \quad x(t_0) = x_0 \tag{1}$$

If  $f$  is continuous in  $t$  and locally Lipschitz continuous in  $x$ , then there exist  $\delta_1, \delta_2 > 0$  such that, for  $x_1$  satisfying  $|x_1 - x_0| < \delta_1$ , the IVP

$$x'(t) = f(t, x), \quad x(t_0) = x_1 \tag{2}$$

has a unique solution on  $(t_0 - \delta_2, t_0 + \delta_2)$ . For  $t_1 \in (t_0 - \delta_2, t_0 + \delta_2)$ , then  $x(t_1)$  is a continuous function of  $x_1$ .