

# Fair Must Testing for I/O Automata

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# The Theory of Testing [DH84]

Consider a model of concurrency that features *automata* and *tests*. It does not matter how they are defined, provided the following:

- ▶ Each test has a set of *states*.
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Normally, automata are tests without success states.

That is, tests are automata enriched with success states.

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- ▶ There is a partial function  $[-||-]$  of type  $tests \times automata \rightarrow tests$ .  
 $[T||A]$  is the *application* of test  $T$  to automata  $A$ . It is of type test.

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Now  $A$  **may pass**  $T$  if  $[T||A]$  has an execution with a success state.

$\uparrow$   
is defined and

$$A \equiv_{\text{may}} B \quad :\Leftrightarrow \quad \forall T. (A \text{ may pass } T \Leftrightarrow B \text{ may pass } T)$$

$$\wedge \text{type}(A) = \text{type}(B).$$

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$$A \sqsubseteq_{\text{may}} B \quad :\Leftrightarrow \quad \forall T. (A \text{ may pass } T \Rightarrow B \text{ may pass } T)$$

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$A$  **must pass**  $T$  if each complete execution of  $[T||A]$  has a success state.

$$A \equiv_{\text{must}} B \quad :\Leftrightarrow \quad \forall T. (A \text{ must pass } T \Leftrightarrow B \text{ must pass } T)$$

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$A$  **should pass**  $T$  [BRV95,NC95] if each finite execution of  $[T||A]$  can be extended into an execution with a success state.

$$A \equiv_{\text{should}} B \quad :\Leftrightarrow \quad \forall T. (A \text{ should pass } T \Leftrightarrow B \text{ should pass } T)$$

$$A \sqsubseteq_{\text{should}} B \quad :\Leftrightarrow \quad \forall T. (A \text{ should pass } T \Rightarrow B \text{ should pass } T) \\ \wedge \text{type}(A) = \text{type}(B).$$

# Testing for CCS [DH84]

automata:  $[\dots]$

tests:  $[\dots]$

states of a test:  $[\dots]$

success states:  $[\dots]$

executions:  $[\dots]$

complete executions:  $[\dots]$

application:  $[\dots]$

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**automata:** CCS expressions, over an alphabet  $\mathcal{A}$  of actions

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**automata:** CCS expressions, over an alphabet  $\mathcal{A}$  of actions

**tests:** CCS expressions, over the alphabet  $\mathcal{A} \uplus \{w\}$

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**complete executions:**  $[\dots]$

**application:**  $[\dots]$

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**states** of a test: the reachable CCS expressions

**success states:**  $[\dots]$

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**application:**  $[\dots]$

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Deadlock: a state without outgoing transitions

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# Automata

An *automaton/test*  $A$  is  $(\text{acts}(A), \text{states}(A), \text{start}(A), \text{steps}(A))$  with

- ▶  $\text{acts}(A)$  a set of *actions*,
- ▶  $\text{states}(A)$  a set of *states*,
- ▶  $\text{start}(A) \subseteq \text{states}(A)$  a nonempty set of *start states*, and
- ▶  $\text{steps}(A) \subseteq \text{states}(A) \times \text{acts}(A) \times \text{states}(A)$  a *transition relation*.

Automata are also known as *process graphs*,  
*state/transition diagrams*, or  
sets of states in *labelled transition systems*.

# Automata

An *automaton/test*  $A$  is  $(acts(A), states(A), start(A), steps(A))$  with

- ▶  $acts(A)$  a set of *actions*, partitioned into two sets  $ext(A)$  and  $int(A)$  of *external actions* and *internal actions*, respectively,
- ▶  $states(A)$  a set of *states*,
- ▶  $start(A) \subseteq states(A)$  a nonempty set of *start states*, and
- ▶  $steps(A) \subseteq states(A) \times acts(A) \times states(A)$  a *transition relation*.

Automata are also known as *process graphs*,  
*state/transition diagrams*, or  
sets of states in *labelled transition systems*.

An *execution* of an I/O automaton  $A$  is an alternating sequence  $\alpha = s_0, a_1, s_1, a_2, \dots$  of states and actions, either being infinite or ending with a state, such that  $s_0 \in start(A)$  and  $(s_i, a_{i+1}, s_{i+1}) \in steps(A)$  for all  $i < length(\alpha)$ .

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# Testing for Automata

**automata:** automata  $A$  (see previous slide) with  $w \notin \text{acts}(A)$

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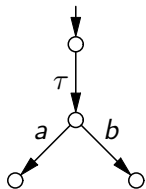
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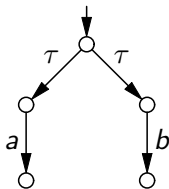
**application:** the CCS context  $(T|A)\backslash\mathcal{A}$  with  $\mathcal{A} = \text{ext}(A) \cup \text{ext}(T)\backslash\{w\}$

The theory of testing for CCS is a special case of the theory of testing for automata.

## Example: discerning branching time

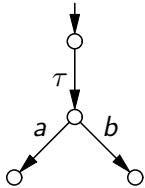


*A*

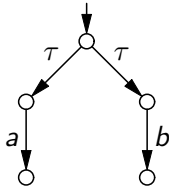


*B*

## Example: discerning branching time



*A*

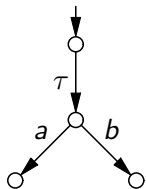


*B*

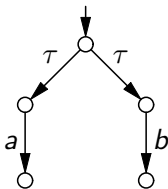


*T*

## Example: discerning branching time



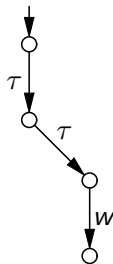
$A$



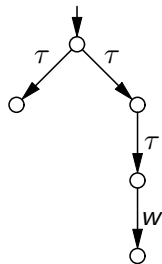
$B$



$T$



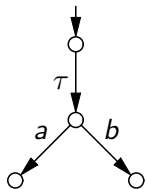
$(T|A)\backslash\mathcal{A}$



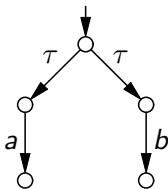
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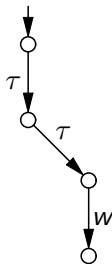
*A*



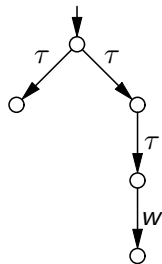
*B*



*T*



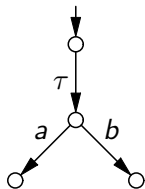
$(T|A) \setminus \mathcal{A}$



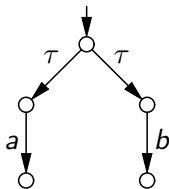
$(T|B) \setminus \mathcal{A}$

***A* must pass *T*    but     $\neg(B \text{ must pass } T)$**

## Example: discerning branching time



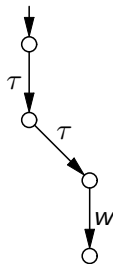
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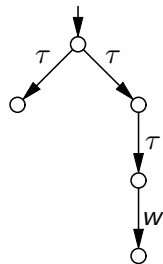
$B$



$T$



$(T|A) \setminus \mathcal{A}$



$(T|B) \setminus \mathcal{A}$

$A$  must pass  $T$  but  $\neg(B \text{ must pass } T)$

Thus  $A \not\sqsubseteq_{\text{must}} B$  and  $A \not\equiv_{\text{must}} B$ .

# Testing for Automata

**automata:** automata  $A$  with  $w \notin \text{acts}(A)$

**tests:** automata  $T$  with  $w \in \text{ext}(T)$

**states of a test:**  $\text{states}(A)$

**success states:** those states in which  $w$  is enabled

**executions:** determined by  $\text{steps}(A)$

**complete executions:** either infinite, or ending in deadlock

**application:** the CCS context  $(T|A) \backslash \mathcal{A}$  with  $\mathcal{A} = \text{ext}(A) \cup \text{ext}(T) \backslash \{w\}$

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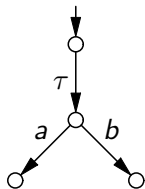
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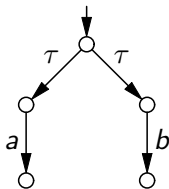
**application:** the CSP parallel composition  $T \parallel A$

This operator enforces synchronisation on  $\text{ext}(T) \cap \text{ext}(A)$ .

## Example: discerning branching time



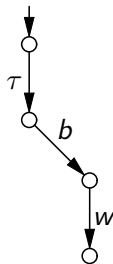
*A*



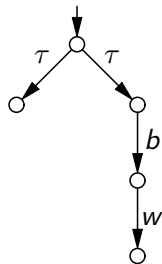
*B*



*T*



$T \parallel A$



$T \parallel B$

**$A$  must pass  $T$  but  $\neg(B \text{ must pass } T)$**

Thus  $A \not\sqsubseteq_{\text{must}} B$  and  $A \not\equiv_{\text{must}} B$ .

# I/O Automata [LT89]

Automata  $A = (\text{acts}(A), \text{states}(A), \text{start}(A), \text{steps}(A))$   
in which

- ▶  $\text{acts}(A)$  is partitioned into  $\text{in}(A)$  and  $\text{out}(A)$ ,
- ▶ such that in each state each action from  $\text{in}(A)$  is enabled,

# I/O Automata [LT89]

Automata  $A = (\text{acts}(A), \text{states}(A), \text{start}(A), \text{steps}(A), \text{part}(A))$   
in which

- ▶  $\text{acts}(A)$  is partitioned into  $\text{in}(A)$  and  $\text{out}(A)$ ,
- ▶ such that in each state each action from  $\text{in}(A)$  is enabled,
- ▶ equipped with a partition  $\text{part}(A)$  of the set  
 $\text{local}(A) := \text{out}(A) \cup \text{int}(A)$  of *locally-controlled actions* of  $A$   
into *tasks*.

# I/O Automata [LT89]

Automata  $A = (\text{acts}(A), \text{states}(A), \text{start}(A), \text{steps}(A), \text{part}(A))$   
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 $\text{local}(A) := \text{out}(A) \cup \text{int}(A)$  of *locally-controlled actions* of  $A$   
into *tasks*.

An execution  $\alpha$  of  $A$  is *fair* if, for each suffix  $\alpha'$  of  $\alpha$   
and each task  $\mathcal{T} \in \text{part}(A)$ ,  
if  $\mathcal{T}$  is enabled in each state of  $\alpha'$ ,  
then  $\alpha'$  contains an action from  $\mathcal{T}$ .



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An execution  $\alpha$  of  $A$  is *fair* if, for each suffix  $\alpha'$  of  $\alpha$   
and each task  $\mathcal{T} \in \text{part}(A)$ ,  
if  $\mathcal{T}$  is enabled in each state of  $\alpha'$ ,  
then  $\alpha'$  contains an action from  $\mathcal{T}$ .

Parallel composition  $A \parallel B$  of I/O automata is as for CSP, or  
standard automata, but is defined only when  $\text{out}(A) \cap \text{out}(B) = \emptyset$ .

## Fundamental Preorders on I/O Automata [LT89]

I/O automata are a *typed* model of concurrency: automata will be compared only when they have the same input and output actions.

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By [GH19, Thm. 6.1] each finite execution can be extended into a fair execution. As a consequence,  $A \sqsubseteq_F B \Rightarrow A \sqsubseteq_T B$ .

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**automata:** automata  $A$  with  $w \notin \text{acts}(A)$

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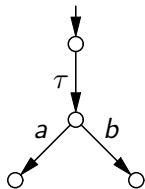
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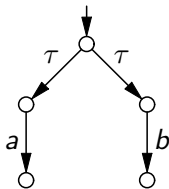
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## Example: discerning branching time impossible



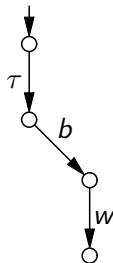
$A$



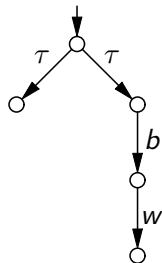
$B$



$T$



$T \parallel A$

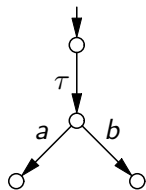


$T \parallel B$

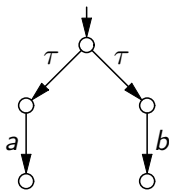
$A$  must pass  $T$  but  $\neg(B \text{ must pass } T)$

Thus  $A \not\sqsubseteq_{\text{must}} B$  and  $A \not\equiv_{\text{must}} B$ .

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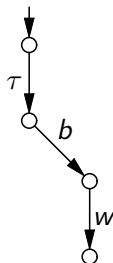
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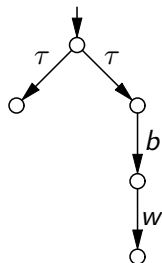
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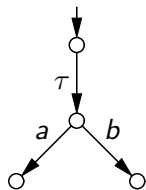


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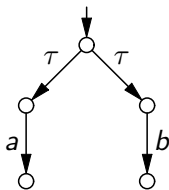
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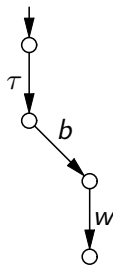
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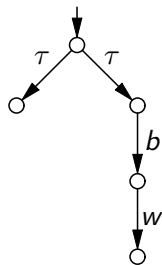
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In fact,  $A \equiv_{\text{must}} B$ .

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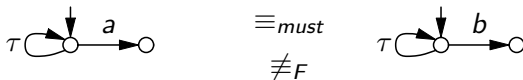
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**Theorem [Seg97]:** Let  $A$  and  $B$  be finitely branching and strongly convergent I/O automata. Then  $A \sqsubseteq_{\text{must}} B$  iff  $A \sqsubseteq_Q B$ .

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In my analysis, this is because the classical theory of testing and I/O automata are based on different notions of a complete execution.

# Testing for I/O Automata based on fairness

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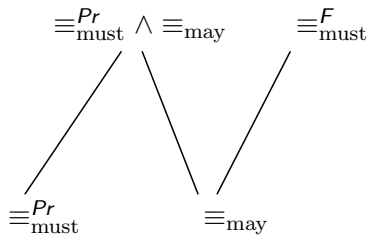
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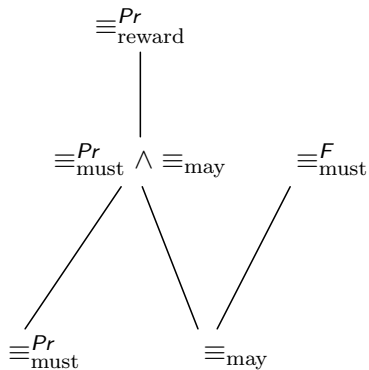
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**Theorem:** Now  $A \sqsubseteq_{\text{must}} B$  iff  $A \sqsubseteq_F B$ .

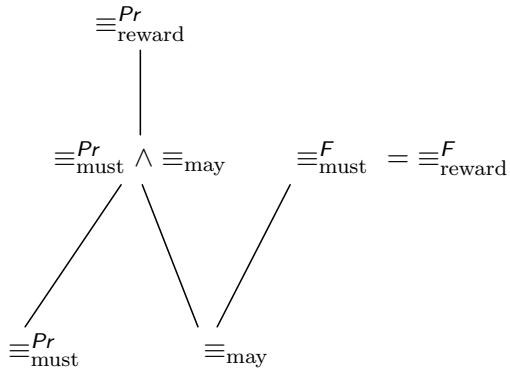
## A lattice of testing equivalences for I/O automata



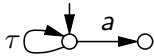
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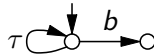


# Counterexamples



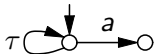
$\equiv_{\text{must}}^{Pr}$

$\not\equiv_{\text{may}}$





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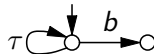


$\not\equiv^{Pr}_{\text{reward}}$

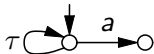
$\equiv^{Pr}_{\text{must}}$

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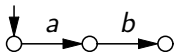
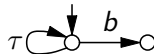


$\not\equiv_{\text{reward}}^{Pr}$

$\equiv_{\text{must}}^{Pr}$

$\not\equiv_{\text{may}}$

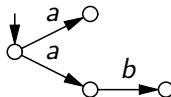
$\not\equiv_{\text{must}}^F$



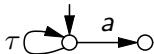
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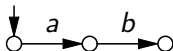
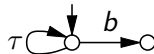


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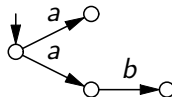


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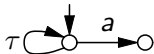
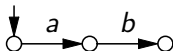
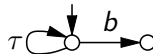
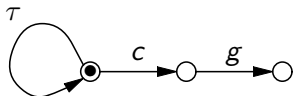
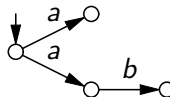
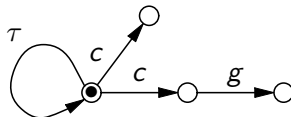
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$\equiv_{\text{may}}$

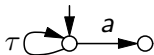
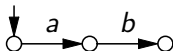
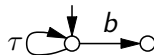
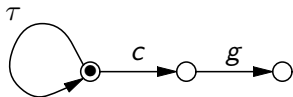
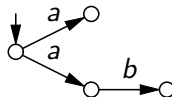
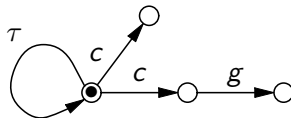
$\not\equiv_{\text{must}}^F$



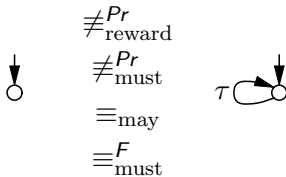
# Counterexamples


 $\neq_{\text{reward}}^{Pr}$ 
 $\equiv_{\text{must}}^{Pr}$ 
 $\neq_{\text{may}}$ 
 $\neq_{\text{must}}^F$ 

 $\neq_{\text{reward}}^{Pr}$ 
 $\neq_{\text{must}}^{Pr}$ 
 $\equiv_{\text{may}}$ 
 $\neq_{\text{must}}^F$ 

 $\neq_{\text{reward}}^{Pr}$ 
 $\equiv_{\text{may}}$ 
 $\equiv_{\text{must}}^{Pr}$ 


# Counterexamples

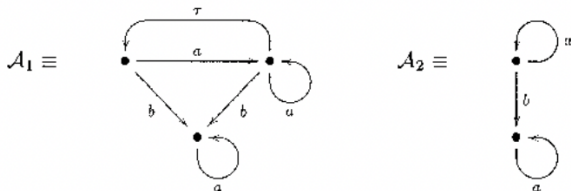

 $\neq_{\text{reward}}^{Pr}$ 
 $\equiv_{\text{must}}^{Pr}$ 
 $\neq_{\text{may}}$ 
 $\neq_{\text{must}}^F$ 

 $\neq_{\text{reward}}^{Pr}$ 
 $\neq_{\text{must}}^{Pr}$ 
 $\equiv_{\text{may}}$ 
 $\neq_{\text{must}}^F$ 

 $\neq_{\text{reward}}^{Pr}$ 
 $\equiv_{\text{may}}$ 
 $\equiv_{\text{must}}^{Pr}$ 
 $\neq_{\text{must}}^F$ 


# Counterexamples



# Counterexamples

EXAMPLE 5.2. Consider the I/O automata



where  $a$  is an input action,  $b$  is an output action,  $\tau$  is an internal action, and the partitions of the locally controlled actions contain a single class. The I/O automata  $\mathcal{A}_1$  and  $\mathcal{A}_2$  are equivalent according to the quiescent preorder since they have the same external traces and their quiescent traces are all finite external traces containing at least a  $b$  action. The external trace  $a^\infty$ , however, is a fair trace of  $\mathcal{A}_1$  but not a fair trace of  $\mathcal{A}_2$ .

$$\mathcal{A}_1 \equiv_{\text{reward}} \mathcal{A}_2 \quad \text{but} \quad \mathcal{A}_1 \not\equiv_{\text{must}}^F \mathcal{A}_2.$$

$$\mathcal{A}_1 \equiv_{\text{must}} \mathcal{A}_2$$

$$\mathcal{A}_1 \equiv_{\text{may}} \mathcal{A}_2$$

# Conclusion

When using the native notion of fairness from I/O automata as completeness criterion in the definition of must testing,

must testing exactly characterises the fair preorder from [LT89].

Upgrading to reward testing here does not yield extra distinctions.

Future work: extend with time and probabilities.