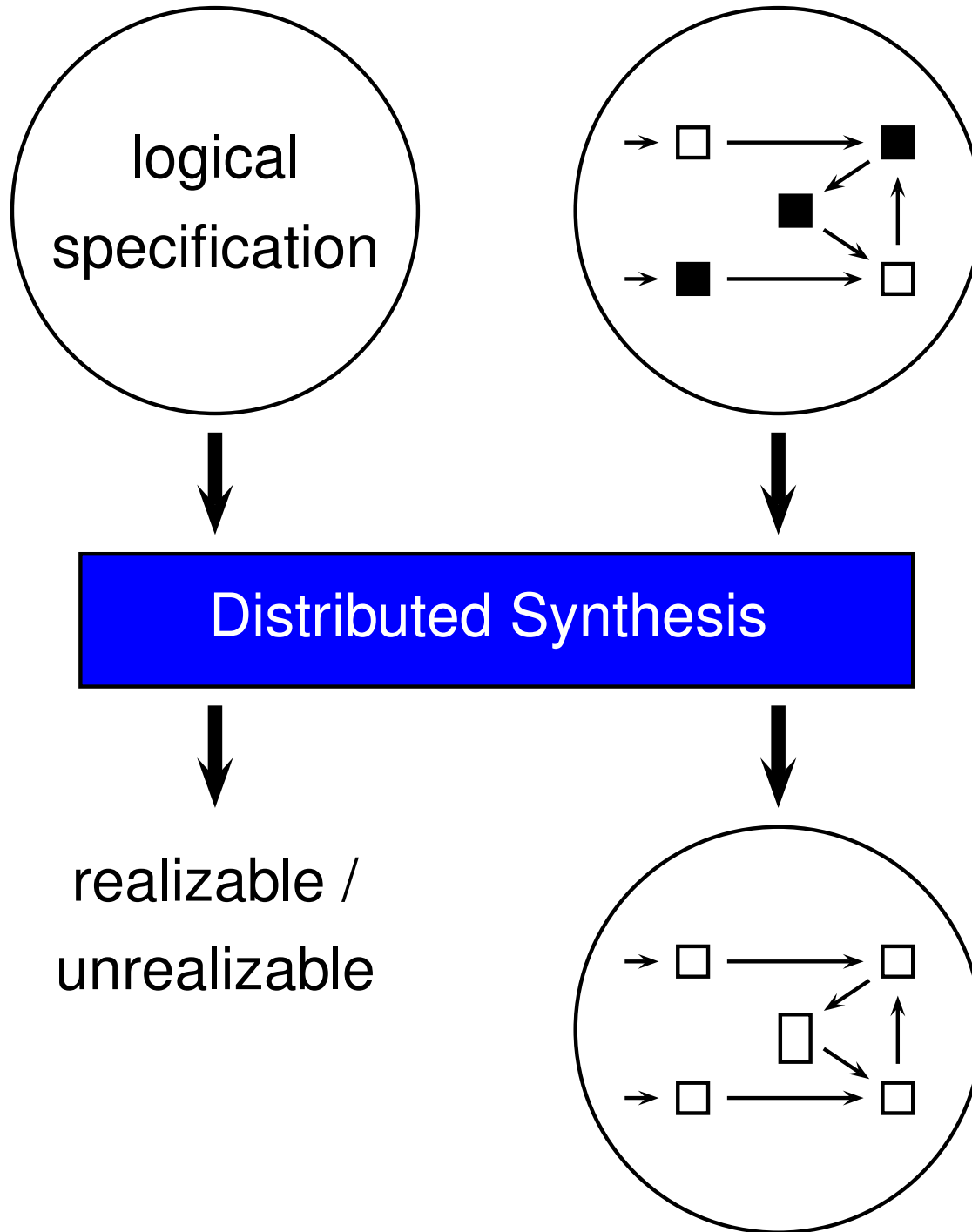


# Petri Games:

## Synthesis of Distributed Systems with Causal Memory

Bernd Finkbeiner & Ernst-Rüdiger Olderog  
Saarbrücken & Oldenburg

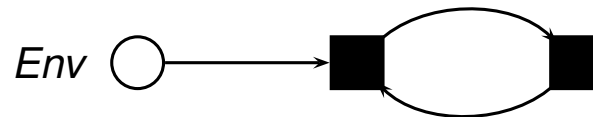




# Models of Distributed Systems

**Pnueli-Rosner model:** synchronous concurrency with **partial observation** of shared variables

- distributed synthesis: in general **undecidable**
- pipelines and rings: **nonelementary**



A. Pnueli & R. Rosner (1990): Distributed Reactive Systems are Hard to Synthesize.

B. Finkbeiner & S. Schewe (2005): Uniform Distributed Synthesis.

# Models of Distributed Systems

**Zielonka automata:** asynchronous concurrency  
with shared actions and **causal memory**

- ▣ distributed synthesis: in general **decidability open**
- ▣ tree architectures: **nonelementary**

Gastin, Lerman & Zeitoun (2004):

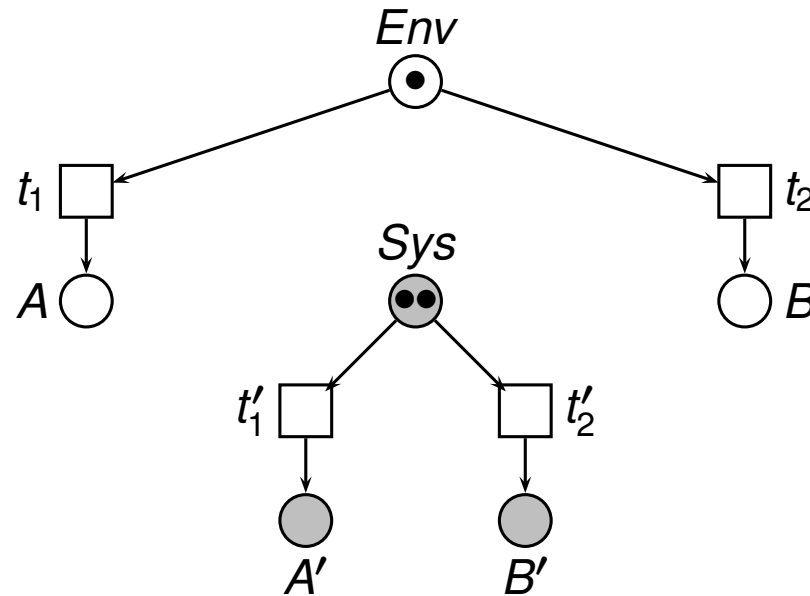
Distributed Games with Causal Memory are Decidable for Series-Parallel Systems.

Genest, Gimbert, Muscholl & Walukiewicz (2013):

Asynchronous Games over Tree Architectures.

# Petri Game: Example

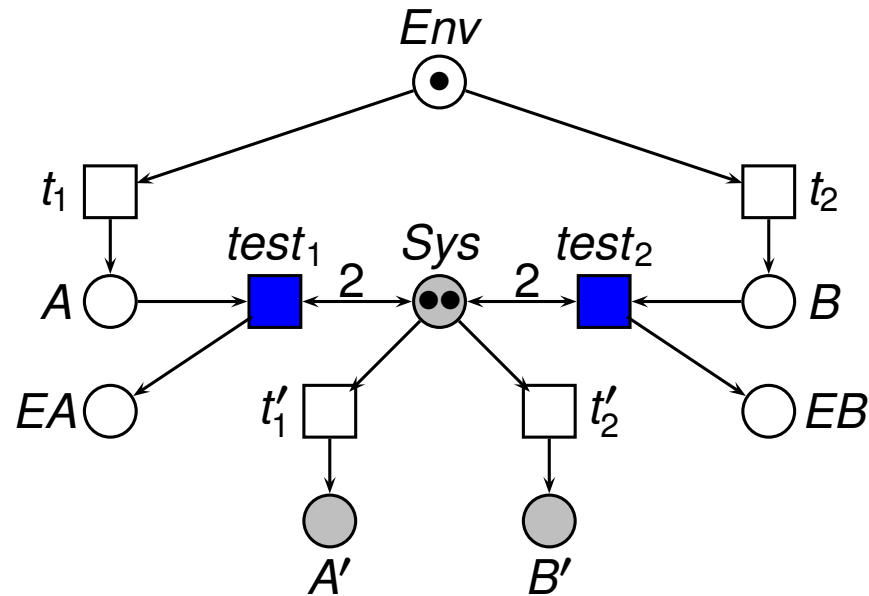
Modelling principle: **causality**



Goal of *Sys*: achieve the same decisions as *Env*.

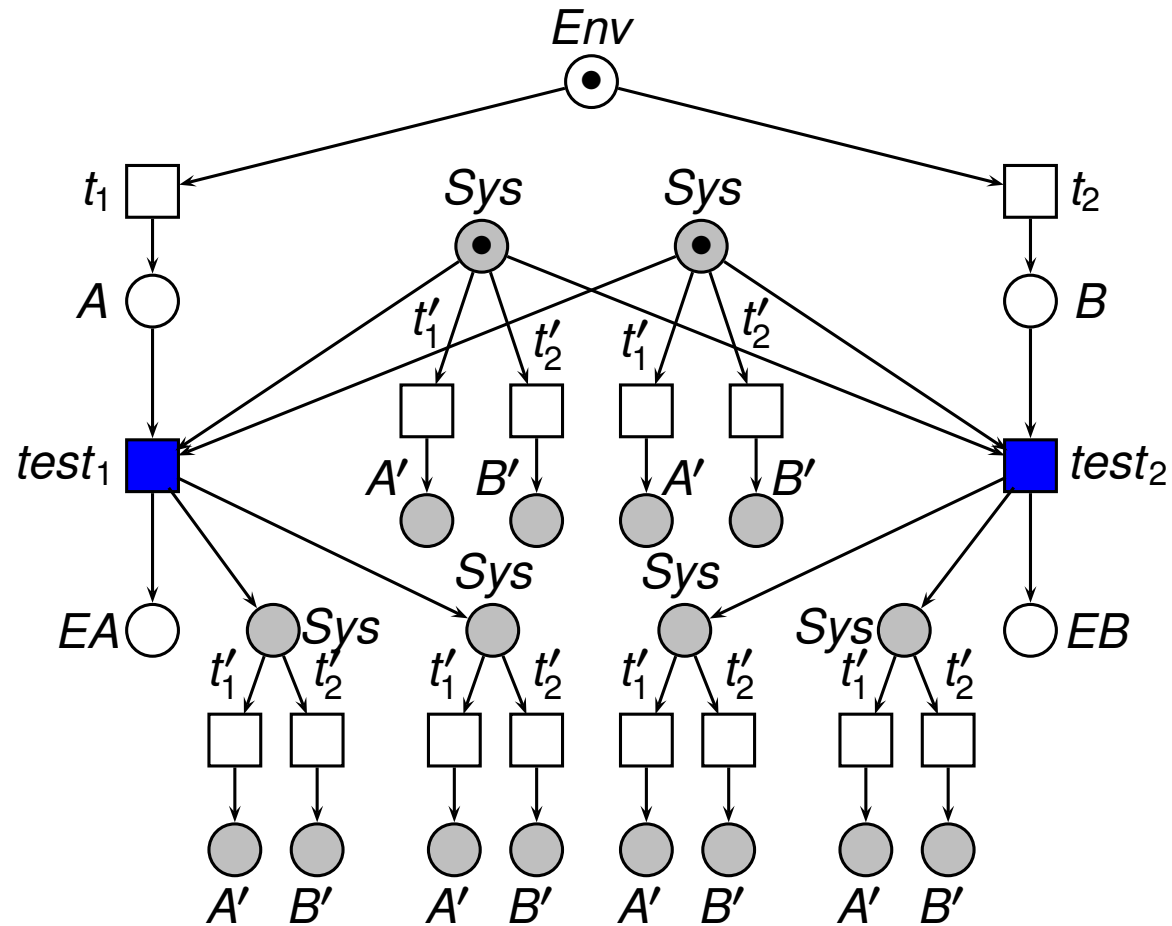
**Problem:** *Sys* **cannot observe** decisions of *Env*.

# Petri Game with Tests



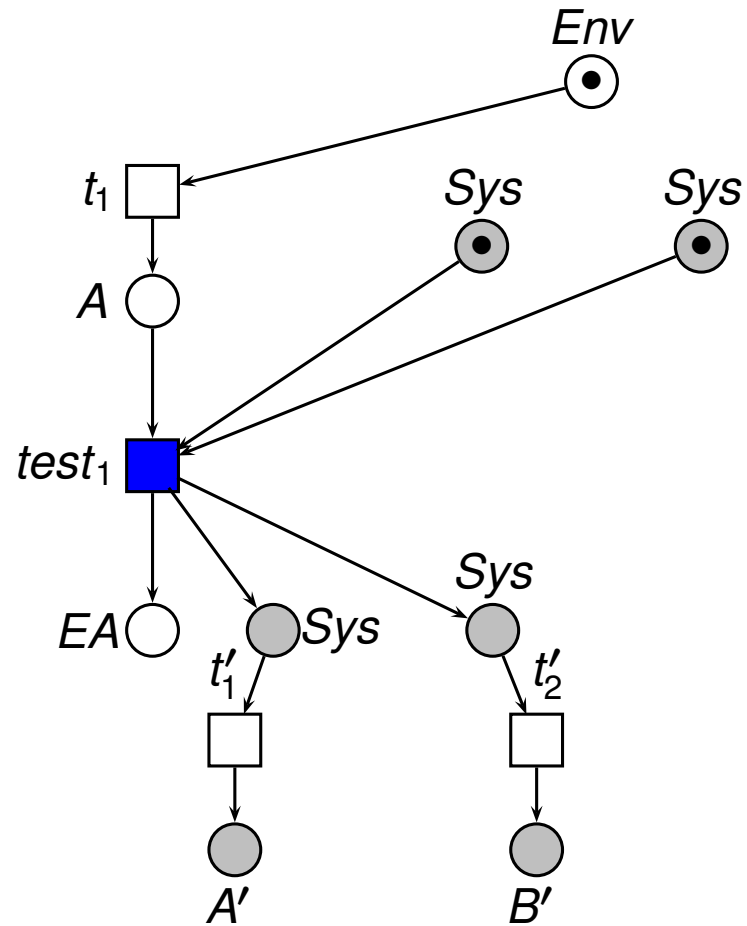
By communicating via transitions  $test_1$  or  $test_2$ ,  $Sys$  learns about decisions of  $Env$ .

# Causality: Unfolding



J. Engelfriet (1991): Branching processes of Petri nets.

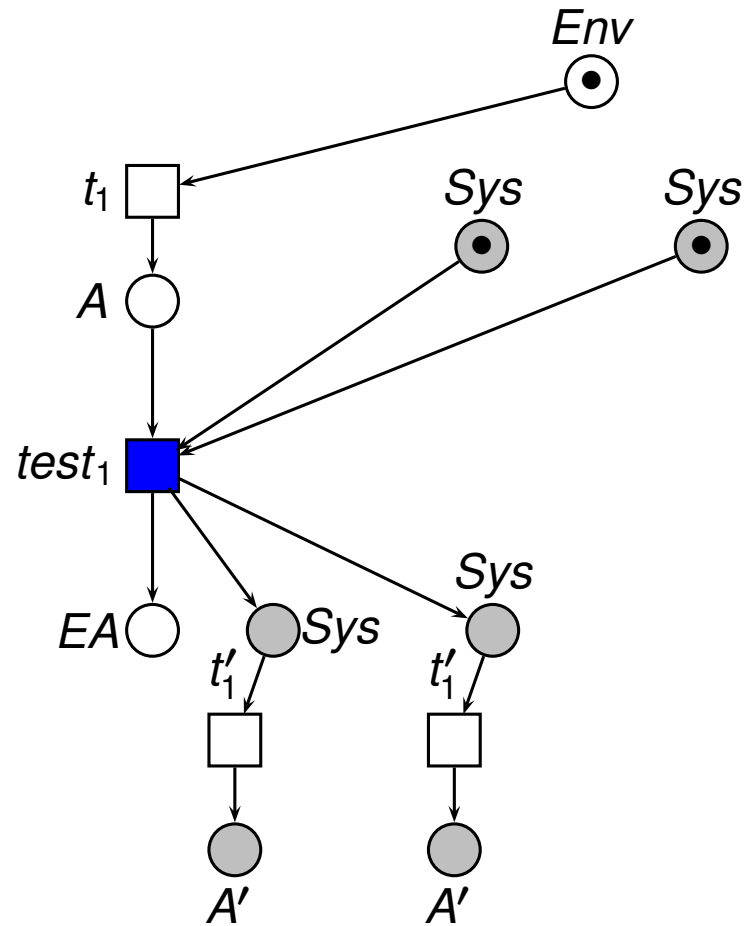
# Play 1



*Env* wins this play.

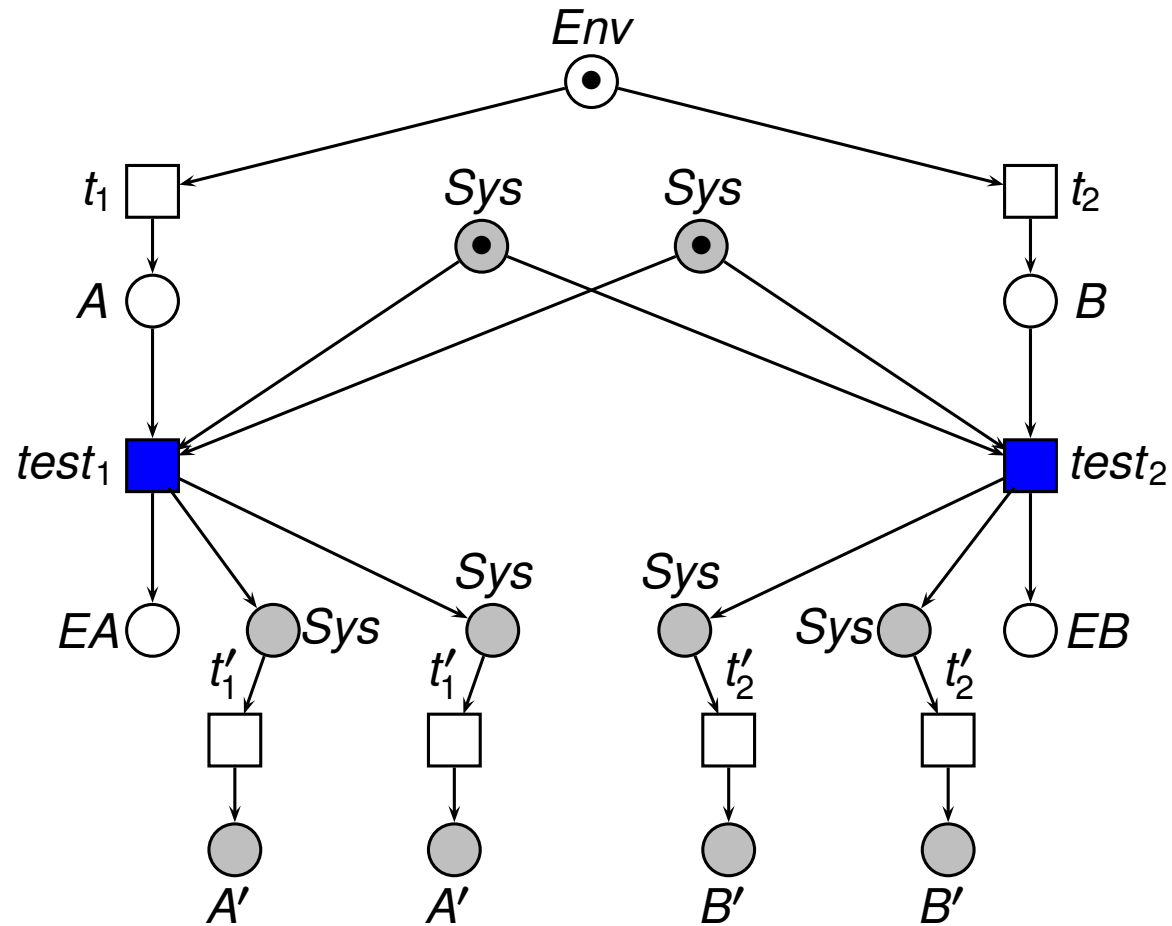


# Play 2



Sys win this play.

# Global Strategy



This is a winning strategy for *Sys*.

# Definition: Global Strategy

A **global strategy** for the system players is a subprocess  $\sigma$  of the unfolding subject to the following conditions:

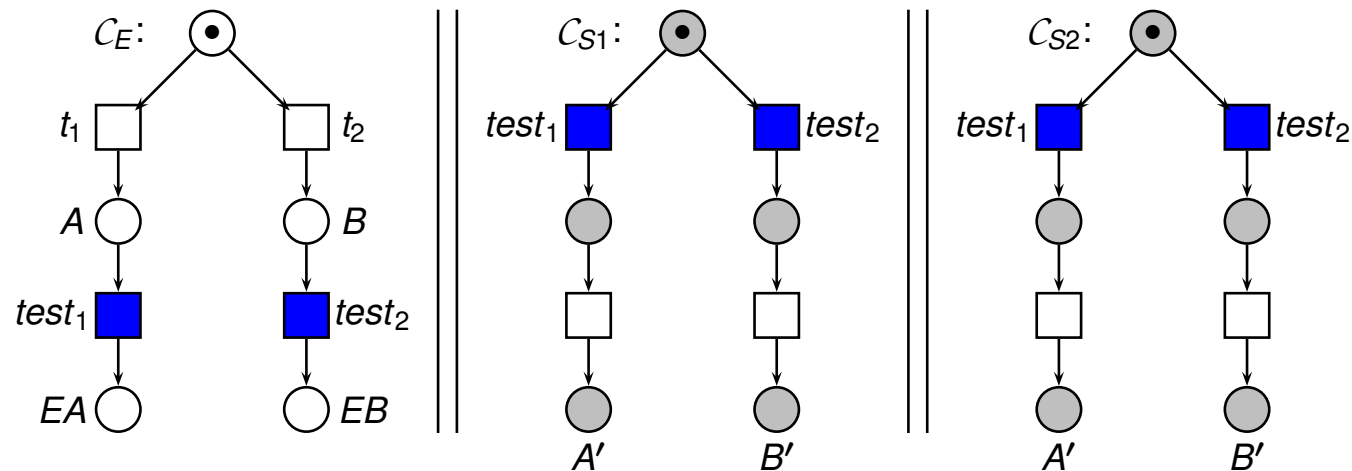
- (S1) at every system place,  $\sigma$  is deterministic,
- (S2) at every environment place,  $\sigma$  does not restrict any local transitions.

A strategy is **deterministic at a place**  $p$  if in every reachable marking at most one transition  $t$  with  $p \in pre(t)$  is enabled.

A strategy is **deadlock-avoiding** if in every reachable marking if there is a transition is enabled in the unfolding then there is some transition enabled in the the strategy.

# Strategy Distribution

A global strategy  $\sigma$  is **distributable** if  $\sigma$  can be represented as the parallel composition of **local controllers** (finite automata) for *Env* and *Sys*.



**Distribution Lemma.** Every global strategy for a concurrency-preserving Petri game is distributable.

# Existence of Winning Strategy

**Question:** Is it decidable ?

Although the **reachability problem** is decidable even for unbounded P/T nets, we have:

**Theorem.** For general Petri games, the question whether the system players have a winning strategy is **undecidable**.

**Idea:** Games on Vector Addition Systems with States are undecidable and can be reduced to Petri games with unbounded markings.

# Solving Petri Games

## EXPTIME-completeness

For bounded Petri games with

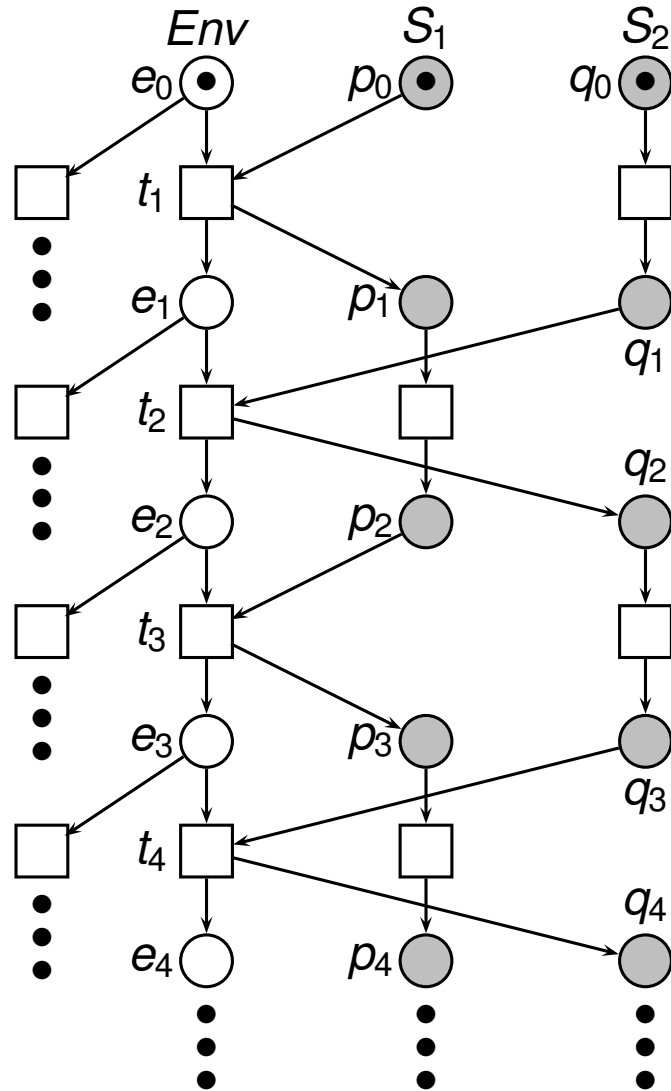
- ➡ one environment player,
- ➡ a bounded number of system players,
- ➡ a safety objective,

the question whether the system players have a winning strategy is **EXPTIME-complete**.

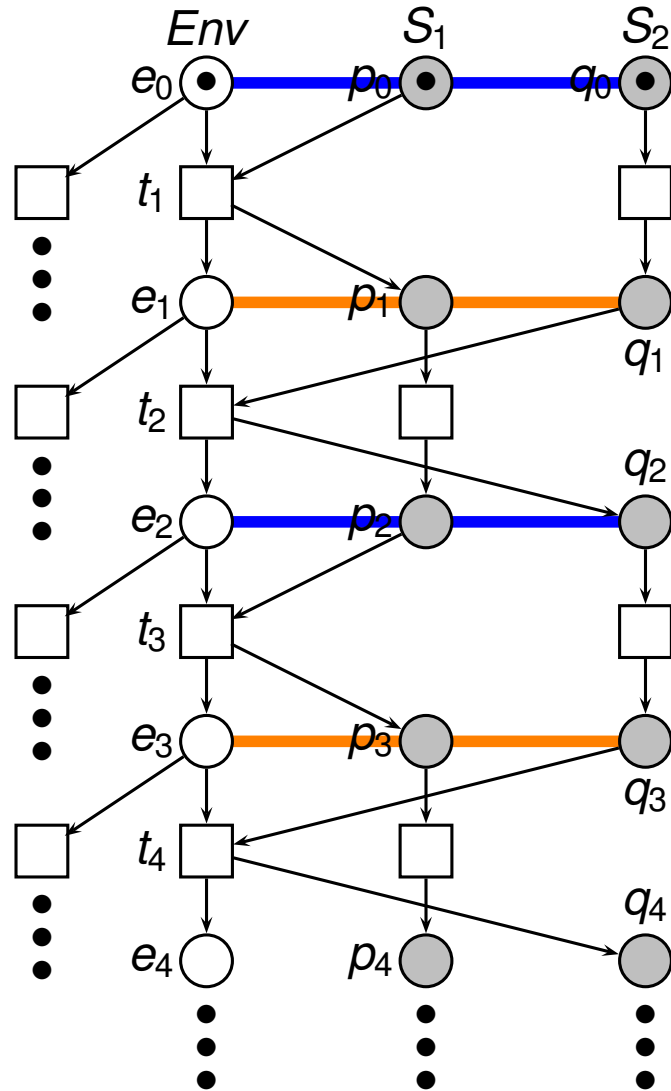
If a winning strategy for the system players exists, it can be constructed in exponential time.

- **Lower bound:** Reduction from combinatorial games
- **Upper bound:** Reduction to 2-player game on finite graphs

# Infinite Strategy



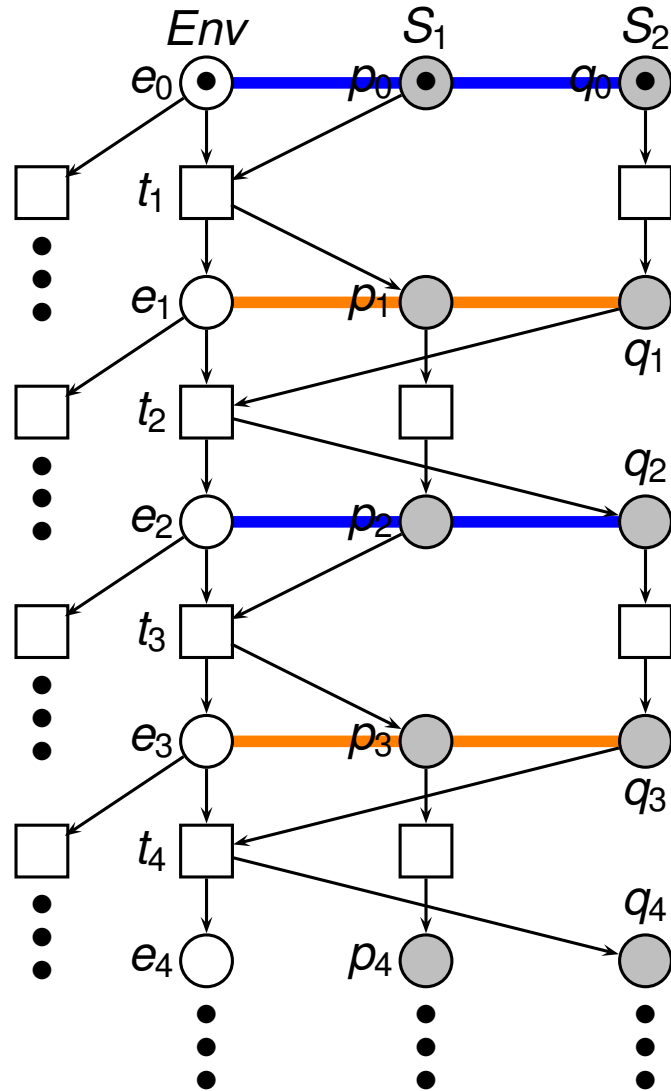
# Cuts



J. Esparza (1994): Model checking using net unfoldings.



# Cuts: changing informedness



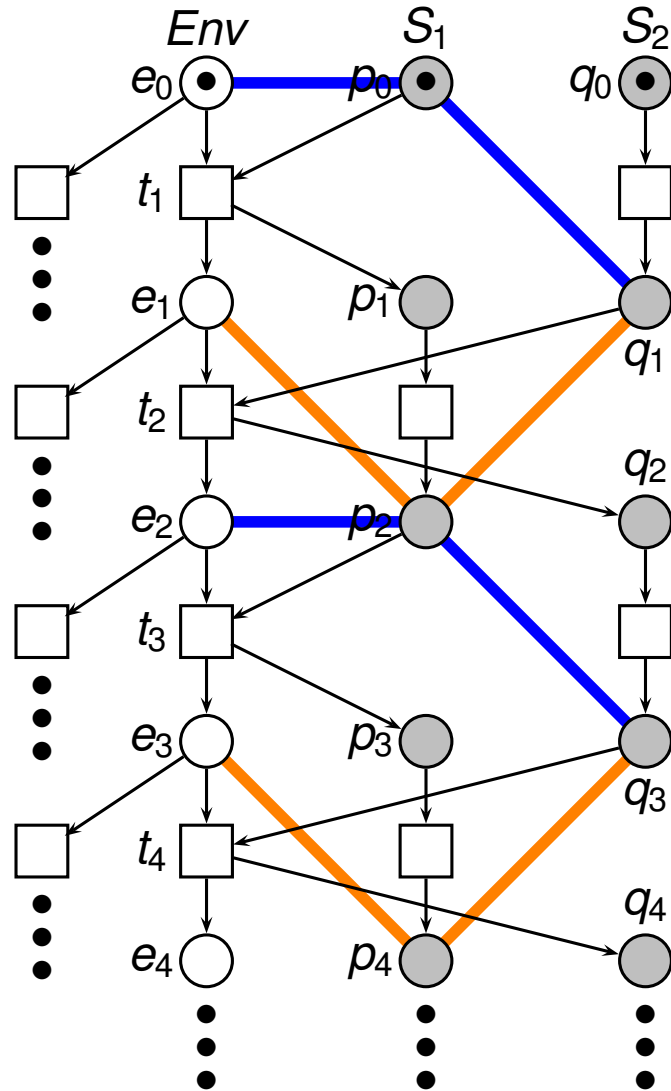
$S_1$  and  $S_2$  know the same.

$S_1$  knows more than  $S_2$ .

$S_2$  knows more than  $S_1$ .

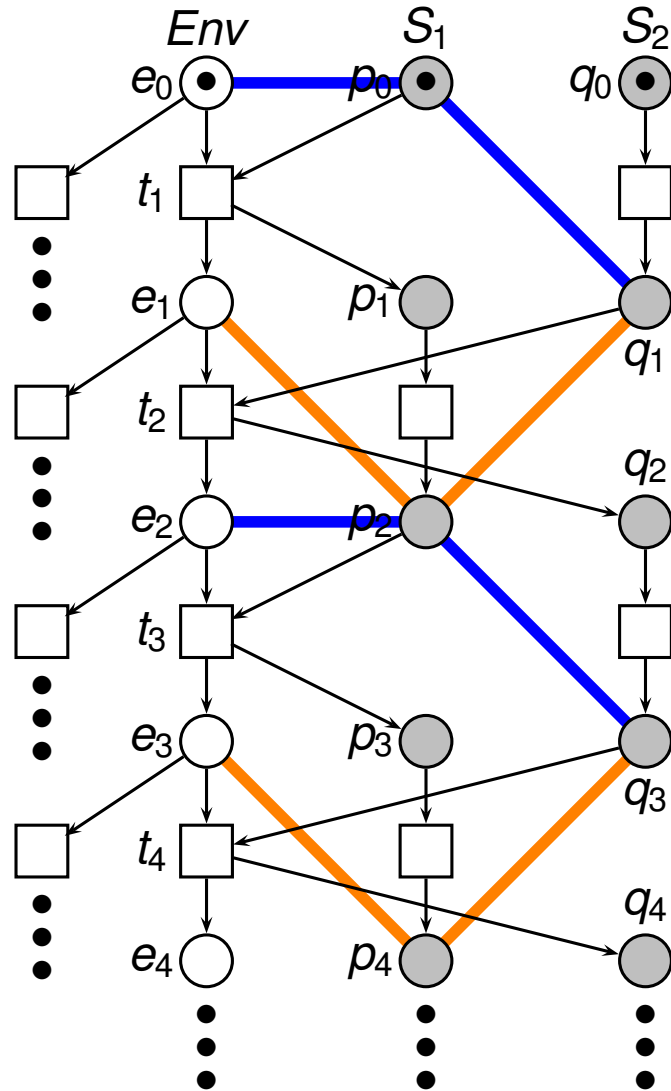
$S_1$  knows more than  $S_2$ .

# Mcuts



System players have maximally progressed.

# Mcuts: equal information



System players have maximally progressed.

# Reduction to Finite-Graph Game

## Reduction Theorem

Every bounded Petri game can be transformed into a finite-graph game of exponential size such that

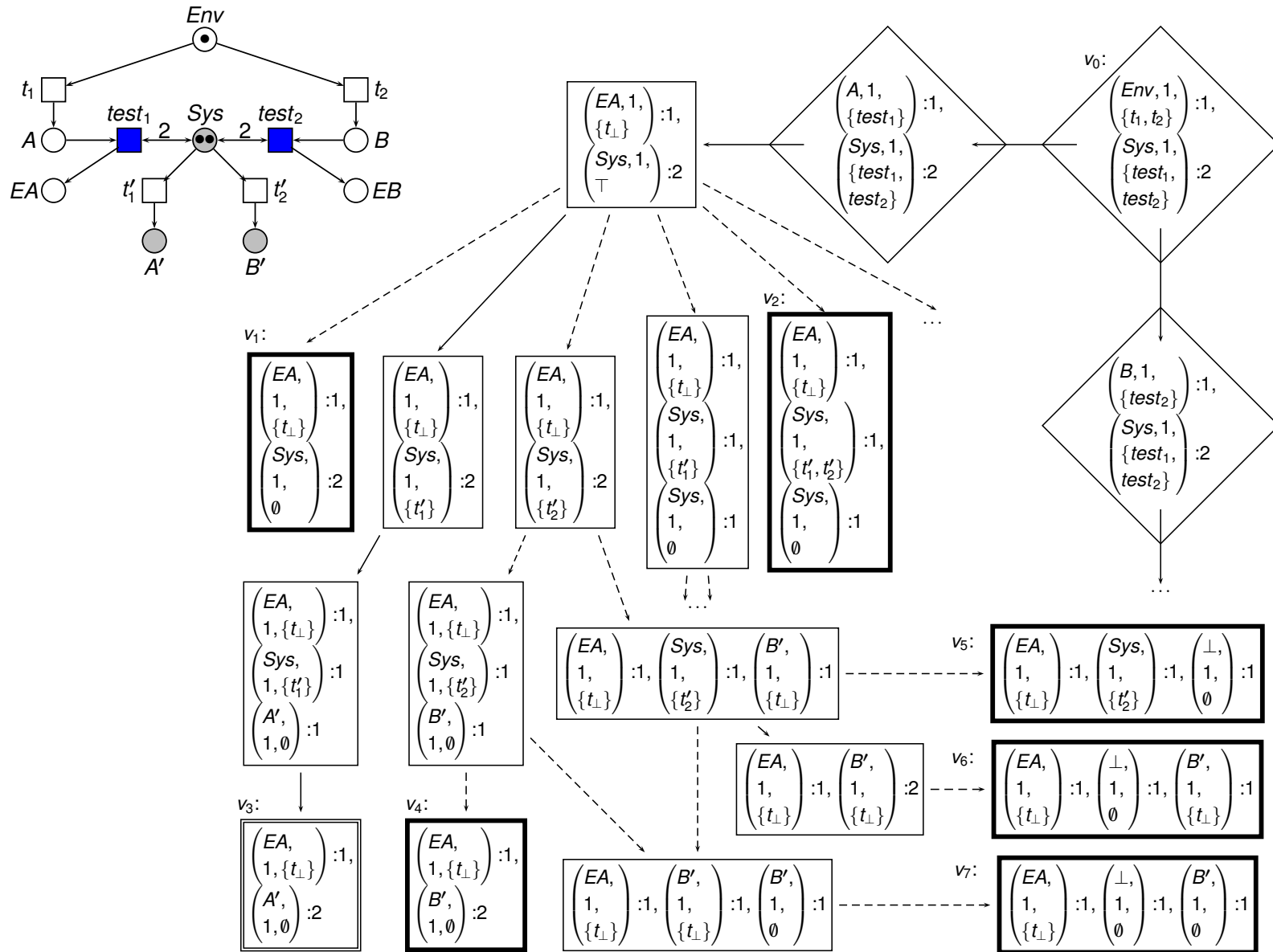
- the system players have a deadlock-avoiding winning strategy iff
- player 0 has a winning strategy in the finite-graph game.

## Idea:

States of the finite-graph game simulate cuts in the net unfolding, more precisely: cuts annotated with sets of outgoing transitions.

Environment decisions are delayed until an mcut is reached.

# Example of a Reduction



# Tool ADAM ...

implements **symbolic game solving algorithm**. It

- ▣▣▣▣▶ inputs a Petri game,
- ▣▣▣▣▶ decides whether a winning strategy exists, and
- ▣▣▣▣▶ if so outputs a winning Petri net strategy for the system players.

ADAM:

- ▣▣▣▣▶ running time only single-exponential in # processes
- ▣▣▣▣▶ automatic synthesis of distributed systems with  $> 30$  processes

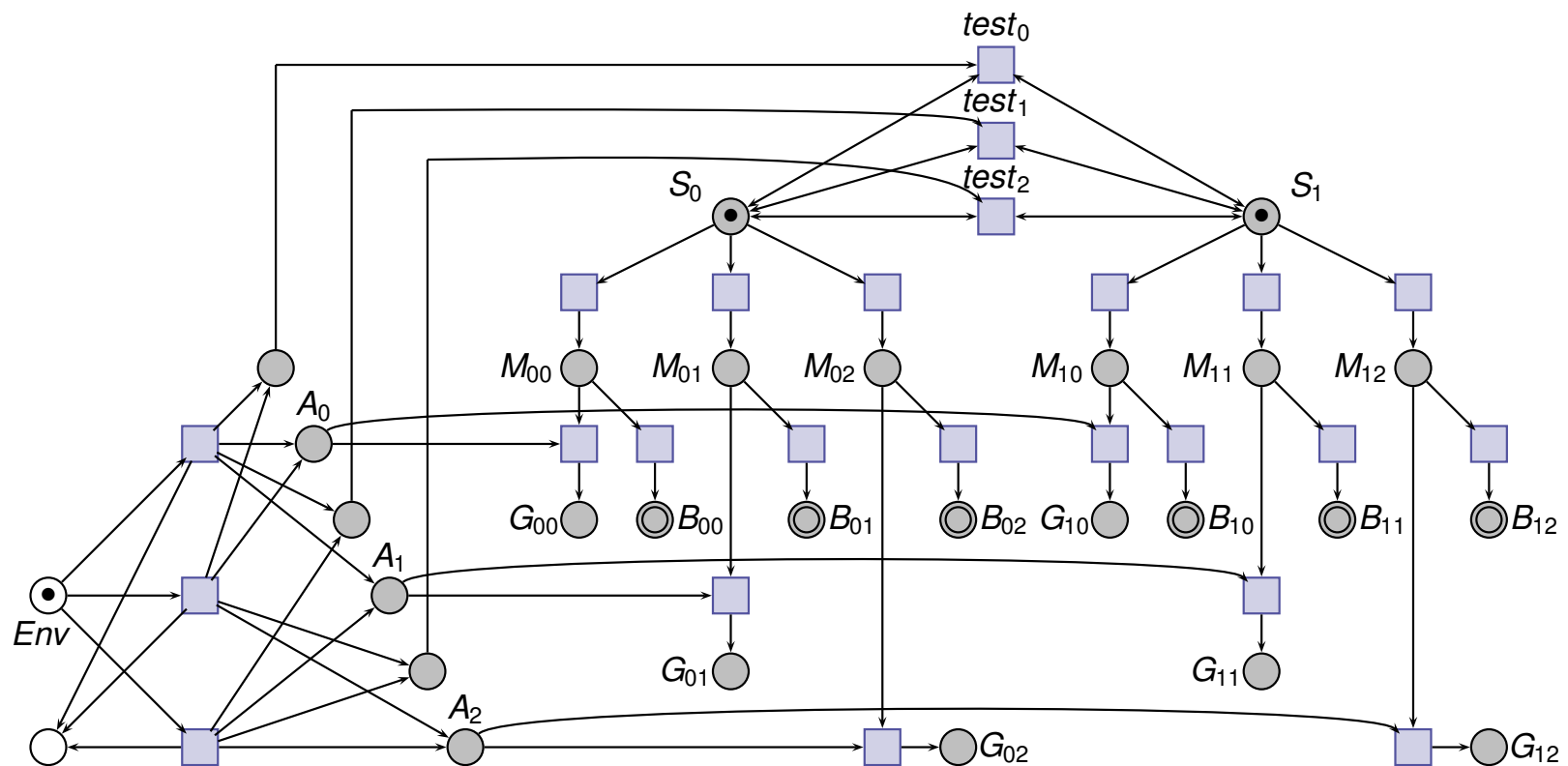
B. Finkbeiner, [Manuel Giese](#) & E.-R. Olderog:

ADAM: Causality-Based Synthesis of Distributed Systems, CAV 2015.

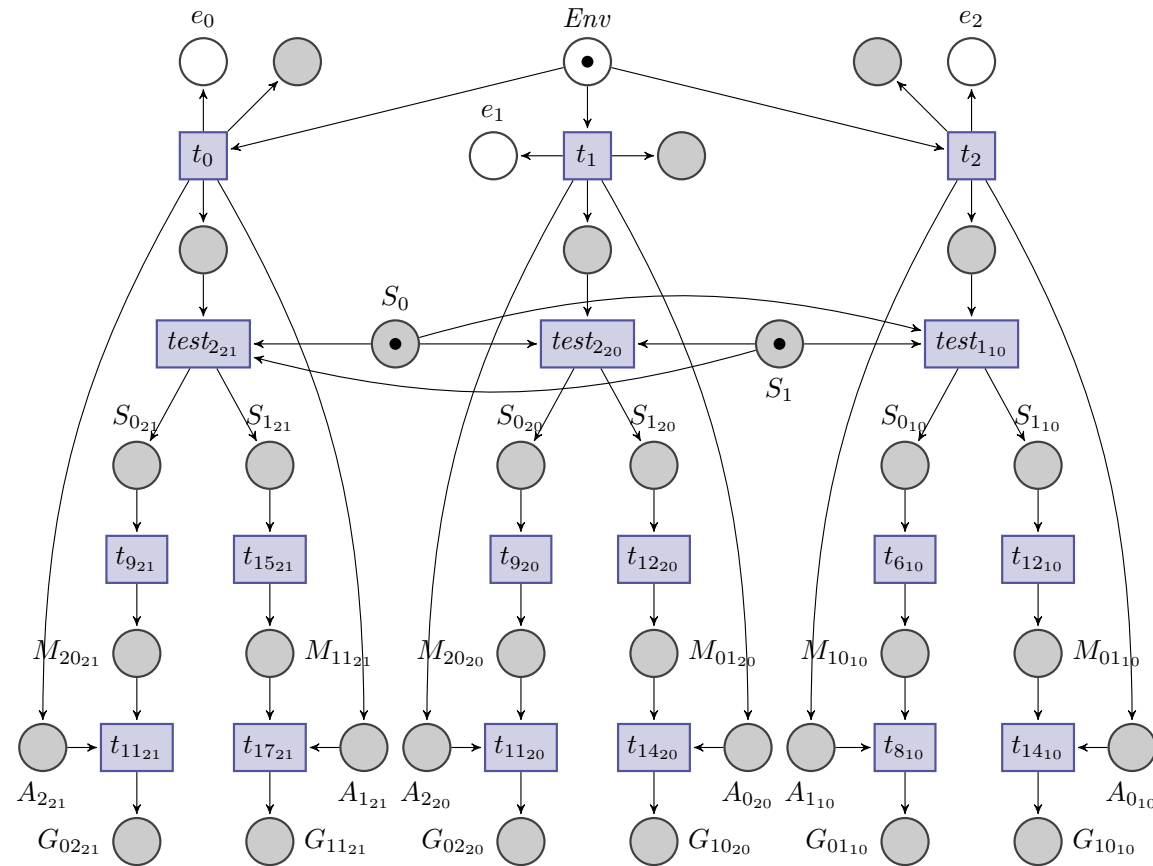
# Concurrent Machines

Robots execute  $k$  orders on  $n$  machines  
in an environment, which may disable an arbitrary machine.

Petri game for  $k = 2$  and  $n = 3$ :

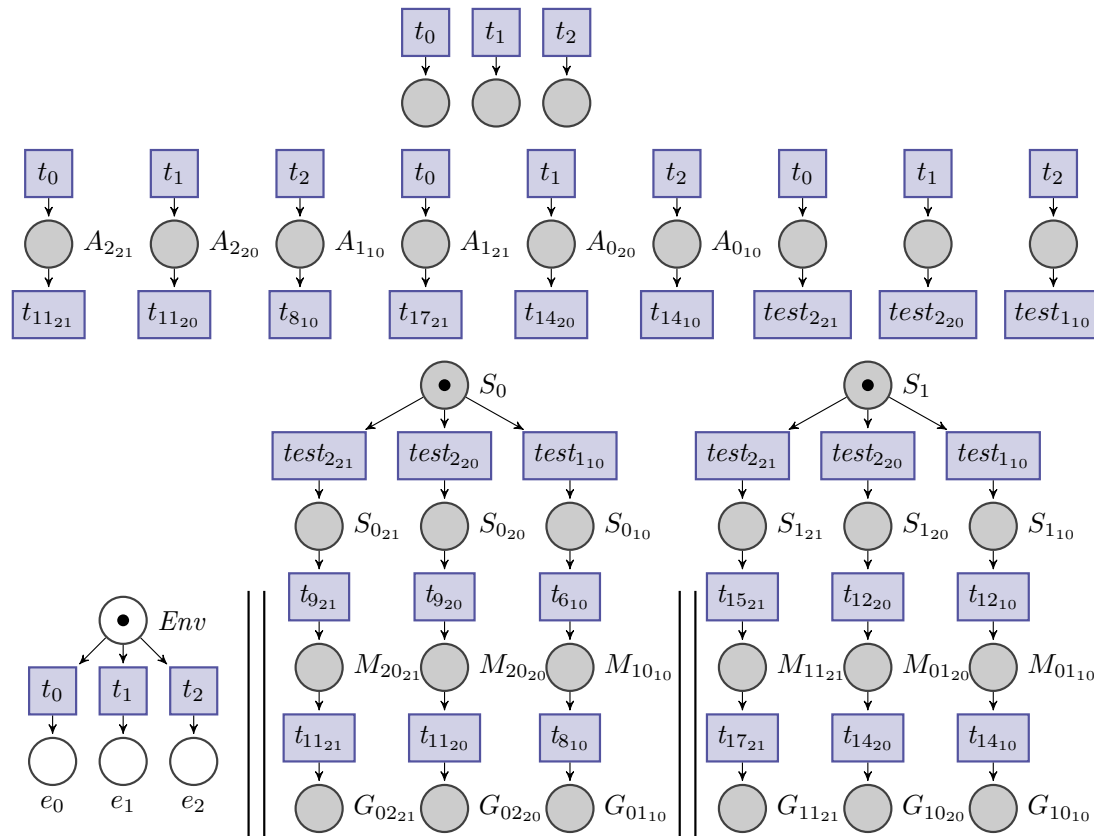


# Petri Game Strategy





# Distributed Controllers



# Further Benchmarks

## ▣▣▣▣➔ SR: Self-reconfiguring Robots

Self-reconfiguration of  $n$  robots on which the environment destroys up to  $k$  tools.

## ▣▣▣▣➔ JP: Job Processing

Processing of a job by a subset of  $n$  processors chosen by the environment.

## ▣▣▣▣➔ DWs: Document Workflow simple

Workflow of a document among  $n$  clerks starting at a clerk selected by the environment.

# Conclusion

Petri games with tool support:

**Distributed** strategies in single-exponential time

Context:

- ▣▣▣▣▶ **one environment token** = one source of information
- ▣▣▣▣▶ causality  $\neq$  partial information
- ▣▣▣▣▶ synthesis without predefined interfaces

# References

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Distributed Reactive Systems are Hard to Synthesize, FOCS 1990.

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