

Program Verification via Higher-Order Model Checking

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What's This Talk About?

- ◆ A survey of applications of **higher-order model checking**
(model checking of higher-order recursion schemes)

to:

**automated verification of
higher-order functional programs**
(e.g. “software model checker” for ML)

Outline

- ◆ **What is higher-order model checking?**
 - higher-order recursion schemes
 - model checking problem
- ◆ **Applications to program verification**
 - verification of finite-data programs
 - verification of infinite-data programs
 - safety properties
 - termination
 - non-termination
 - general liveness properties
- ◆ **Conclusion**

Higher-Order Recursion Scheme (HORS)

- ◆ Grammar for generating an infinite tree

Order-0 HORS
(regular tree grammar)

$$S \rightarrow a \ c \ B$$
$$B \rightarrow b \ S$$

$S \rightarrow a \ c \ B$

$B \rightarrow b \ S$

Higher-Order Recursion Scheme (HORS)

◆ Grammar for generating an infinite tree

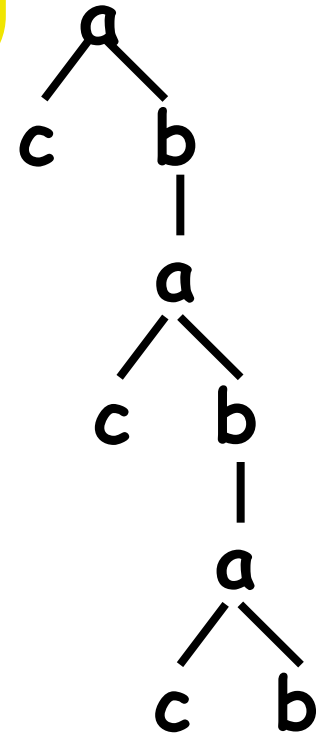
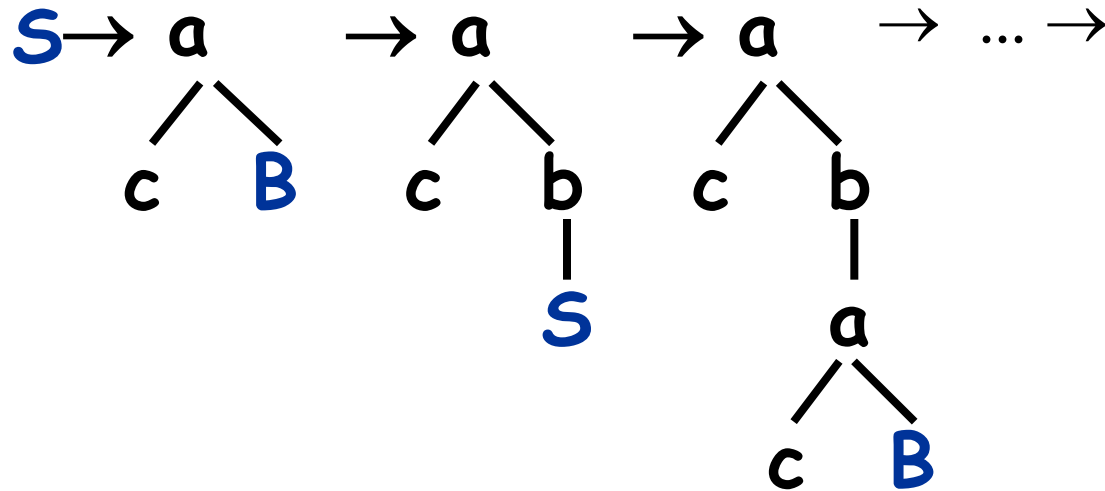
Order-0 HORS
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$S \rightarrow a \ c \ B$

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$S \rightarrow a$
 $\swarrow \searrow$
 $c \quad B$

$B \rightarrow b$
 $|$
 S



Higher-Order Recursion Scheme (HORS)

◆ Grammar for generating an infinite tree

Order-1 HORS

$$S \rightarrow A c$$
$$A x \rightarrow a x (A (b x))$$
$$S: o, A: o \rightarrow o$$

Higher-Order Recursion Scheme (HORS)

◆ Grammar for generating an infinite tree

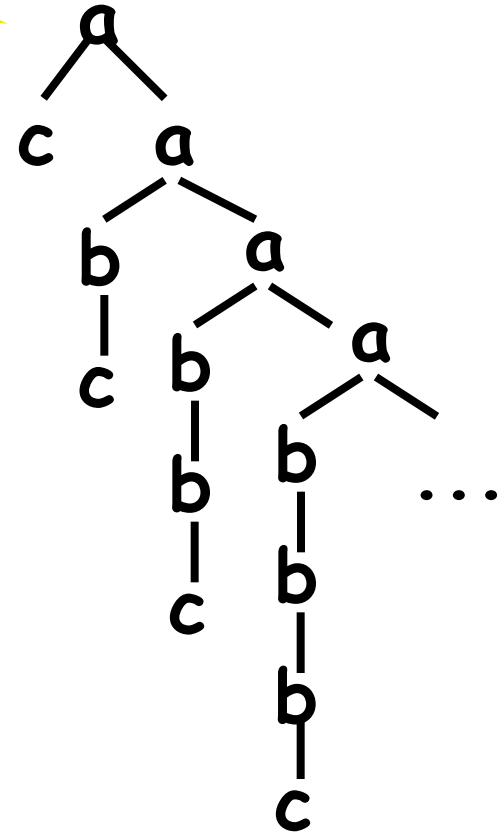
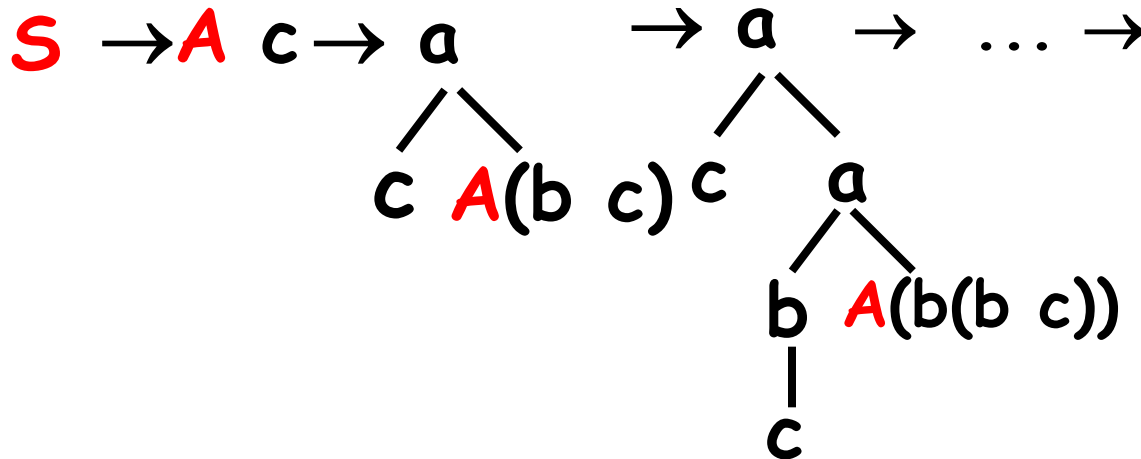
Order-1 HORS

$S \rightarrow A c$

$A x \rightarrow a x \quad (A (b x))$

$S: o, A: o \rightarrow o$

Tree whose paths are labeled by $a^{m+1} b^m c$



Higher-Order Recursion Scheme (HORS)

◆ Grammar for generating an infinite tree

Order-1 HORS

$$S \rightarrow A c$$
$$A x \rightarrow a x (A (b x))$$

$S: o$, $A: o \rightarrow o$

HORS

\approx

Call-by-name simply-typed λ -calculus

+

recursion, tree constructors

Higher-Order Model Checking

Given

G : HORS

A : alternating parity tree automaton
(a formula of modal μ -calculus or MSO),
does A accept $\text{Tree}(G)$?

e.g.

- Does every finite path end with "c"?
- Does "a" occur below "b"?

Higher-Order Model Checking

Given

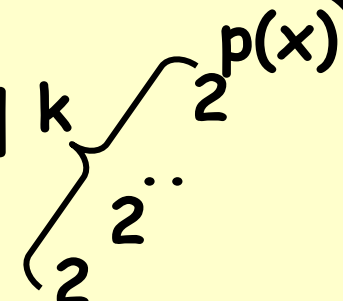
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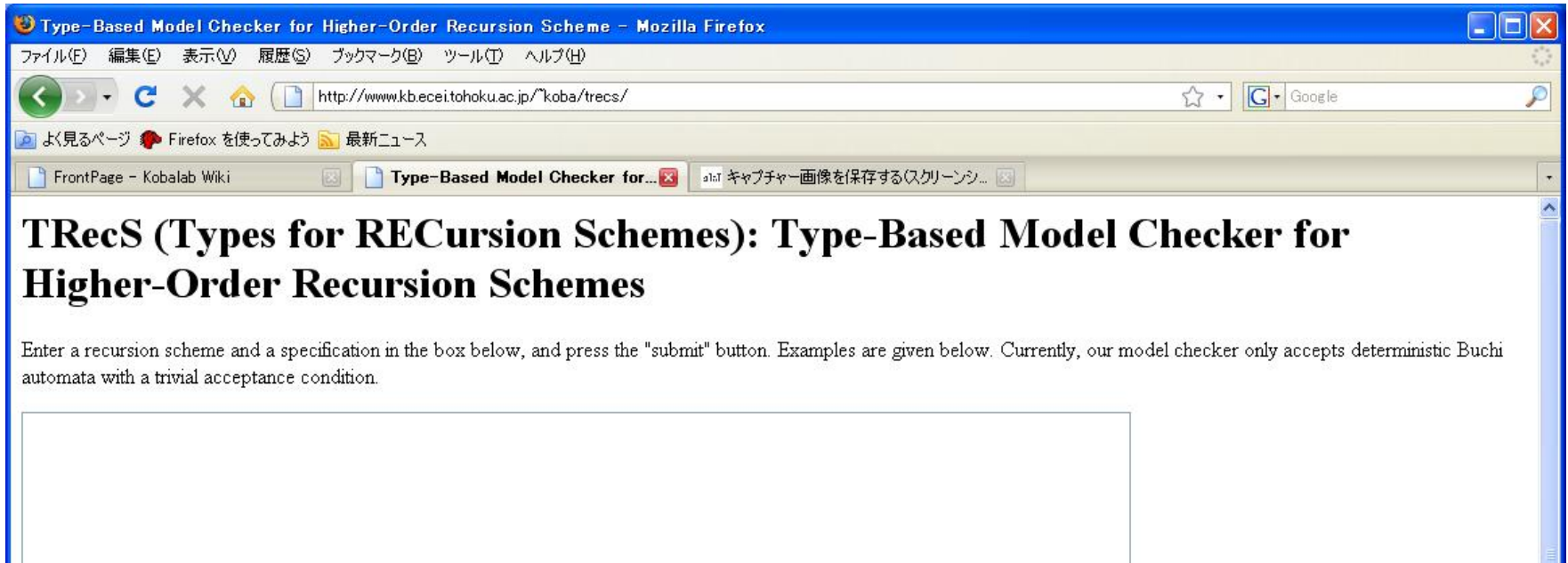
- Does every finite path end with "c"?
- Does "a" occur below "b"?

k -EXPTIME-complete [Ong, LICS06]
(for order- k HORS)



TRecS [K. PPDP09]

<http://www-kb.is.s.u-tokyo.ac.jp/~koba/trecs/>



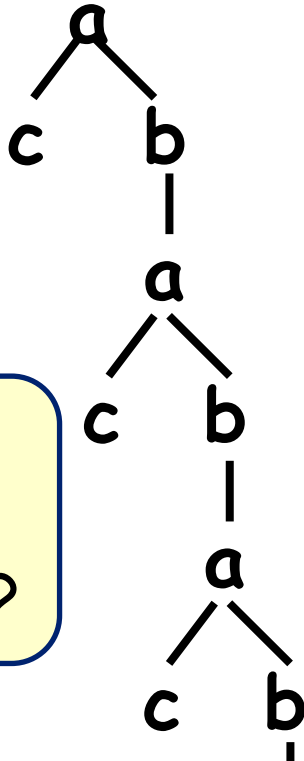
- ◆ The first **practical** model checker for HORS
- ◆ Does not immediately suffer from k -EXPTIME bottleneck

q0 a -> q0 q0. /* The first state is interpreted as the initial state. */
q0 b -> q1.

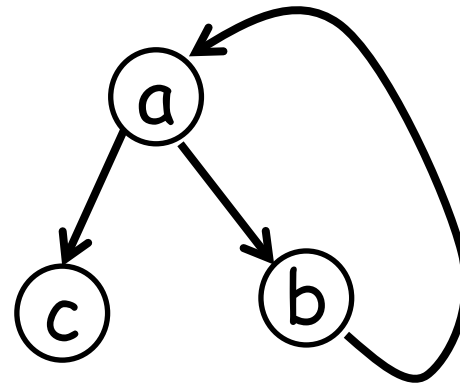
HO Model Checking as Generalization of Finite State/Pushdown Model Checking

- ◆ order-0 \approx finite state model checking
- ◆ order-1 \approx pushdown model checking

infinite tree \approx transition system

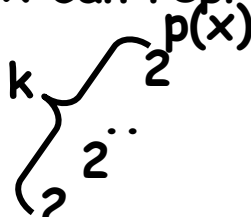


Does "a" occur below "b"?

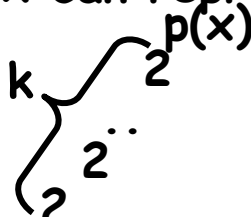


Is there a transition sequence in which "a" occurs after "b"?

Why HO Model Checking Works? (despite k-EXPTIME completeness)

- ◆ Fixed-parameter polynomial time in the size of grammars (under certain assumptions)
 - ◆ A “certificate” can be checked in polynomial time (cf. NP problems)
 - ◆ For finite-state models, HO model checking can actually be faster than finite state model checking
 - HORS can compactly represent finite-state systems
 - An order-k HORS of size x can represent a system with states
- 
$$\left. \begin{array}{l} 2^{2^{p(x)}} \\ 2^i \end{array} \right\} k$$
- k-EXPTIME algorithm for HO model checking
 \approx PTIME algorithm for finite-state model checking

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A diagram consisting of a large curly bracket on the left side. The bracket is labeled with the letter 'k' at its top end. The bracket encompasses two mathematical expressions: $2^{p(x)}$ at the top and 2^i at the bottom.

- **PTIME algorithm** for HO model checking

>> PTIME algorithm for finite-state model checking

Outline

◆ What is higher-order model checking?

- higher-order recursion schemes
- model checking problem

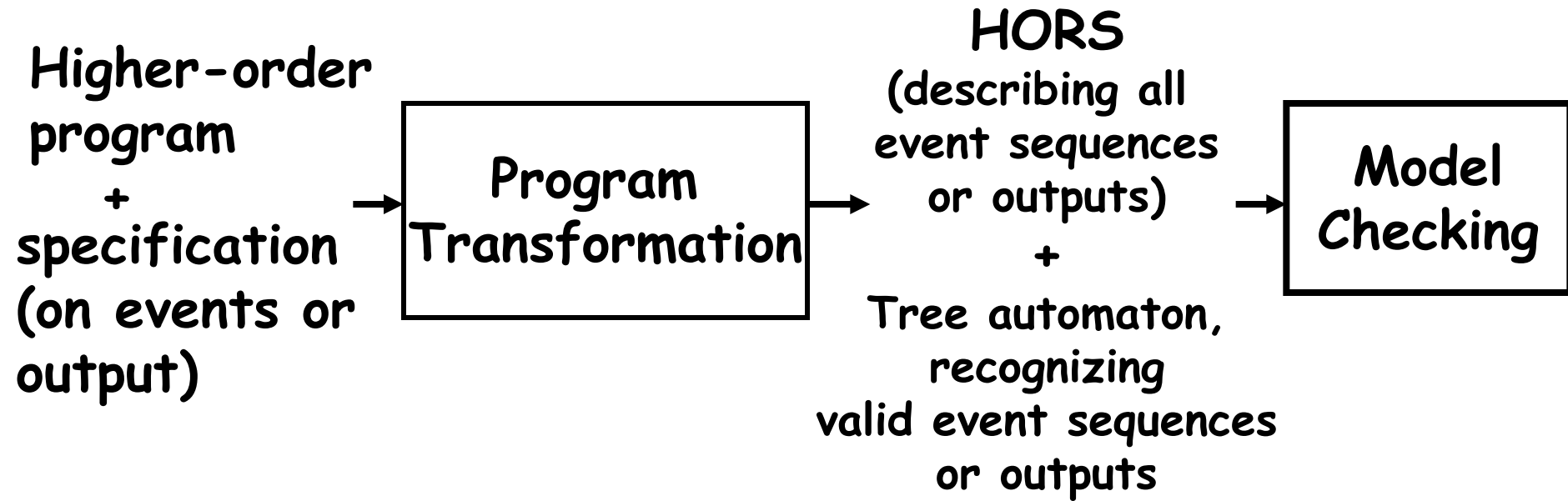
◆ Applications to program verification

- verification of finite-data HO programs
- verification of infinite-data HO programs
 - safety properties [K+ PLDI 2011]...
 - termination [Kuwahara+ ESOP 2014]
 - non-termination [Kuwahara+ CAV 2015]
 - general liveness properties (ongoing)

◆ Conclusion

From Program Verification to HO Model Checking

[K. POPL 2009]

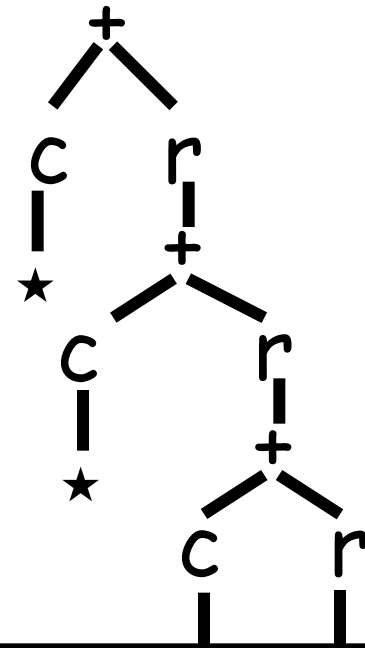


From Program Verification to Model Checking: Example

```
let f(x) =  
  if * then close(x)  
  else read(x); f(x)  
in  
let y = open "foo"  
in  
  f(y)
```

$F \times k \rightarrow + (c \ k) (r(F \times k))$

$S \rightarrow F \ d \ \star$



Is the file "foo"
accessed according
to read* close?

Is each path of the tree
labeled by r^*c ?

From Program

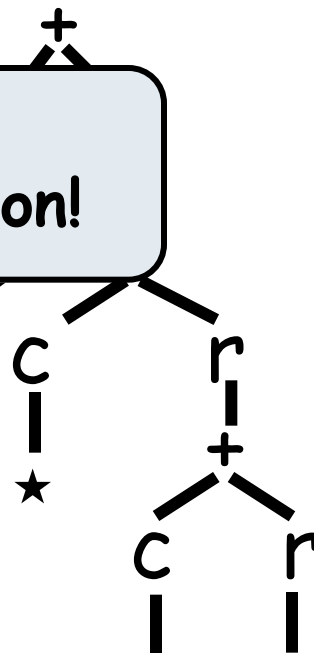
continuation parameter,
expressing how "foo" is
accessed after the call returns

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CPS
Transformation!



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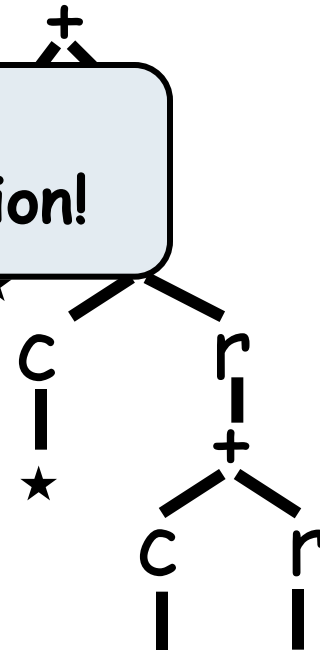
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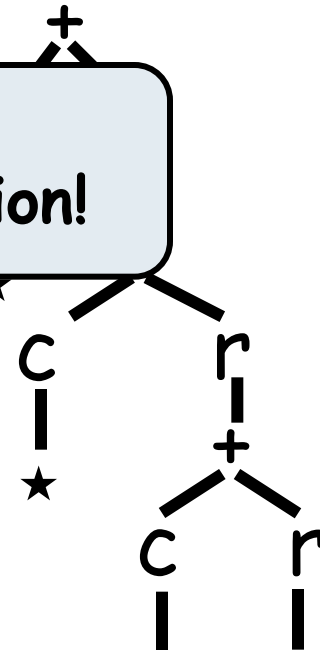
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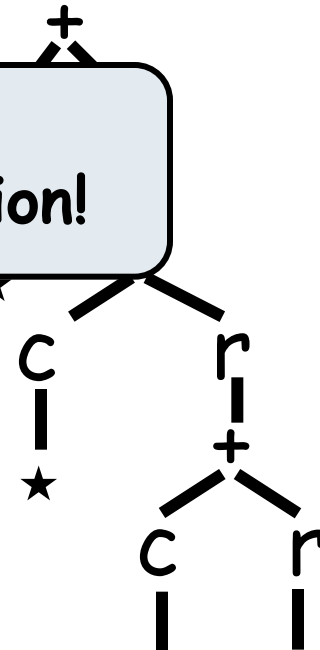
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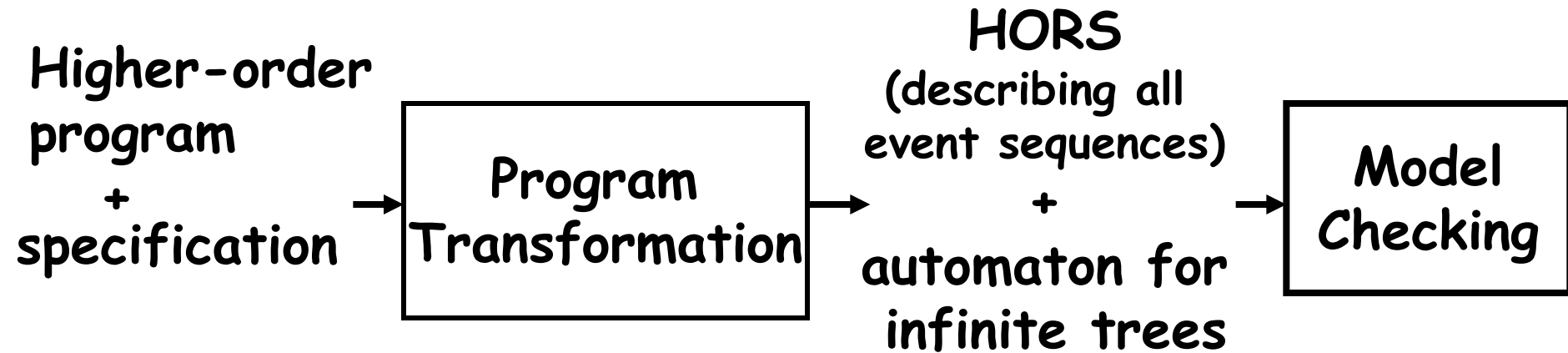
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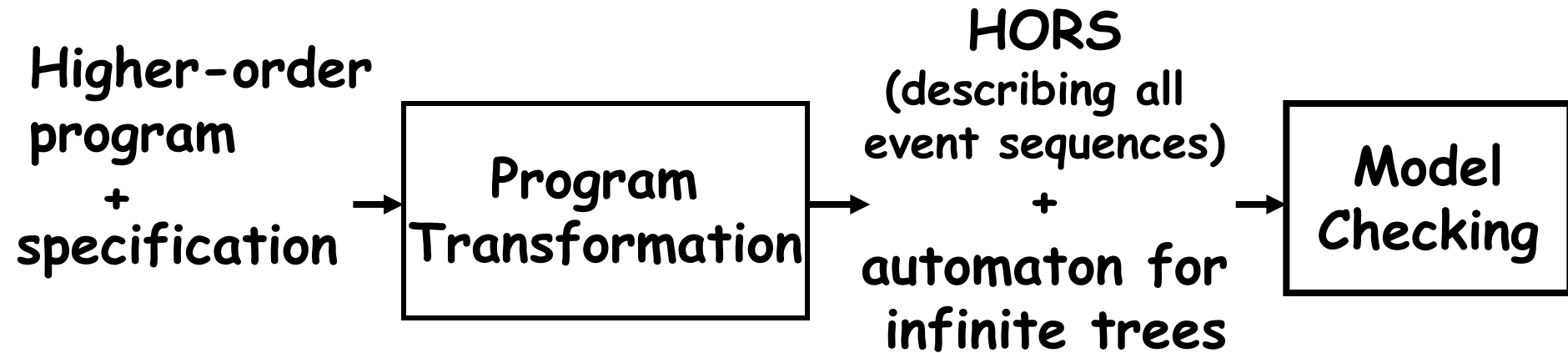
From Program Verification to HO Model Checking



Sound, complete, and automatic for:

- A large class of higher-order programs:
simply-typed λ -calculus + recursion
+ finite base types (e.g. booleans) + exceptions + ...
- A large class of verification problems:
resource usage verification (or typestate checking),
reachability, flow analysis, strictness analysis, ...

From Program Verification to HO Model Checking



**For finite-data HO programs,
automated verification comes almost free
from HO model checking!**

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 - termination
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Verification of Higher-order Programs with Infinite Data (integers, lists, trees, ...)

- ◆ For safety properties (e.g. reachability), overapproximation by abstraction of infinite data suffice.
- ◆ For other properties (e.g. termination), combinations of problem reduction and abstraction are required.

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Predicate Abstraction and CEGAR for Higher-Order Model Checking

[K.&Sato&Unno, PLDI2011]

$f(g, x) = g(x+1)$

Higher-order functional program

$\lambda x. x > 0$

Predicate abstraction

New predicates

Higher-order boolean program

$F(g, b) =$
if b then $g(\text{true})$
else $g(*)$

Program is unsafe!

Real error path?

yes

Error path

property not satisfied

Higher-order model checking

property satisfied

Program is safe!

Dealing with algebraic data types (e.g. lists)

◆ Abstraction approach:

- automata-based [K+ POPL10][Unno+ APLAS 10]...
- pattern-based [Ong&Ramsay POPL11]

◆ Encoding approach [Sato+ PEPM13] :

- algebraic data as functions

[τ list] = ^{length function from indices to elements} $\text{int} \times (\text{int} \rightarrow [\tau])$

$\text{nil} = (0, \lambda x. \text{fail})$

$\text{cons} = \lambda x. \lambda(\text{len}, f).$

$(\text{len}+1, \lambda i. \text{if } i=0 \text{ then } x \text{ else } f(i-1))$

$\text{hd}(\text{len}, f) = f(0)$

...

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Termination Verification

- ◆ Goal: prove that a program terminates for every input (and non-determinism)
- ◆ Naive approach: abstract a program to a finite data program, and apply HO model checking
 - Problem: many terminating programs are turned into non-terminating ones by abstraction
 - e.g. $f(x) = \text{if } x < 0 \text{ then } 1 \text{ else } 1 + f(x - 1)$ terminating
 - $\rightarrow f(b_{x < 0}) = \text{if } b_{x < 0} \text{ then } 1 \text{ else } 1 + f(*)$ non-terminating
- ◆ Our approach [Kawahara+, ESOP14]
(cf. [Rybalchenko&Podelski] for termination of imperative programs):
 - Reduce termination to *binary reachability*
 - Reduce binary reachability to *plain* reachability

From Termination to Binary Reachability for HO Programs

- ◆ Every non-terminating computation must contain an infinite chain of recursive calls:

$\text{main}() \rightarrow^* C_0[f v_0]$

$f v_i \rightarrow^+ C_{i+1}[f v_{i+1}]$ for $i=0,1,2,\dots$

for some function f

- ⇒ A sufficient (and necessary) condition for termination:

$\text{Call}_f = \{ (v, w) \mid \text{main}() \rightarrow^* C[f v], f v \rightarrow^+ D[f w] \}$

is **well-founded** for every function f

- ⇒ To prove termination, it suffices to

- pick a well-founded relation W_f ; and

- prove $\text{Call}_f \subseteq W_f$

for each f

From Binary Reachability to Plain Reachability

- ◆ Goal: check $\text{Call}_f \subseteq W_f$
(where $\text{Call}_f = \{(v, w) \mid \text{main}() \rightarrow^* C[f\ v], f\ v \rightarrow^+ D[f\ w]\}$)
- ◆ Approach: reduction to a plain reachability problem by program transformation
 - To each function, add an extra argument to record the argument of an ancestor call of f .
 - Assert that W_f holds when f is called

```
fib n =  
  if n < 2 then n  
  else fib(n-1)+fib(n-2)  
main() = fib(rand())
```

```
 $W_{\text{fib}} = \{(m, n) \mid m > n \geq 0\}$ 
```



```
fib m n =  
  assert(m > n ≥ 0);  
  let m' = if * then m else n in  
  if n < 2 then n  
  else fib m' (n-1)+fib m' (n-2)  
main() = fib ⊥ (rand())
```

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Verifying Non-Termination (or Disproving Termination) of HO programs

- ◆ Goal: prove that a program is **non-terminating** for **some** input (or for some non-deterministic choice)
 - complementary to termination verification
- ◆ Unsound approach: overapproximate a program by a finite data program, and apply HO model checking
$$f(x) = \text{if } x < 0 \text{ then } 1 \text{ else } 1 + f(x-1) \quad \text{terminating}$$
$$\rightarrow f(b_{x < 0}) = \text{if } b_{x < 0} \text{ then } 1 \text{ else } 1 + f(*) \quad \text{non-terminating}$$
- ◆ Our approach [Kuwahara+, CAV15]:
 - combine **over- and under-approximation**
 - construct a program that outputs an approximation of the computation tree of the original program
 - use HO model checking to check that the computation tree contains infinite computation

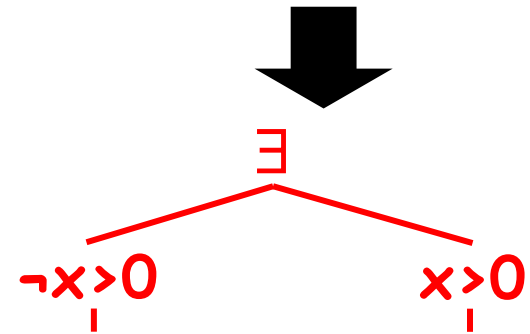
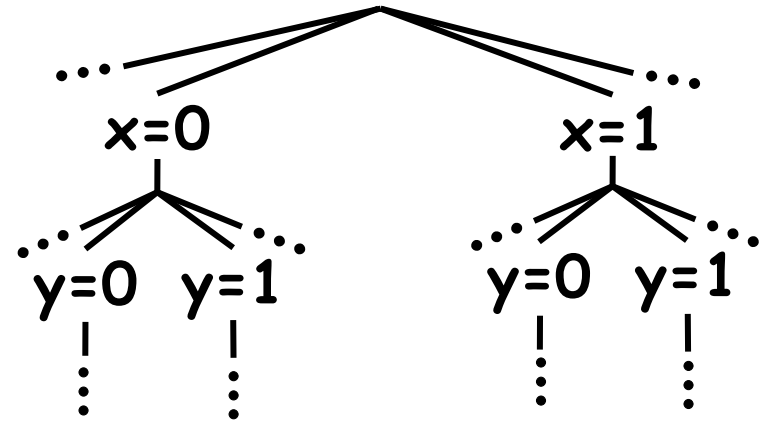
Our Approach: Combination of Under-/Over-approximation

pred: $x > 0$

```
let x=* in  
let y=* in  
f(x+y)
```

Only one of the
branches needs to
be non-terminating

```
∃ (...  
  /* case  $\neg x > 0$  */  
  , ...  
  /* case  $x > 0$  */  
)
```



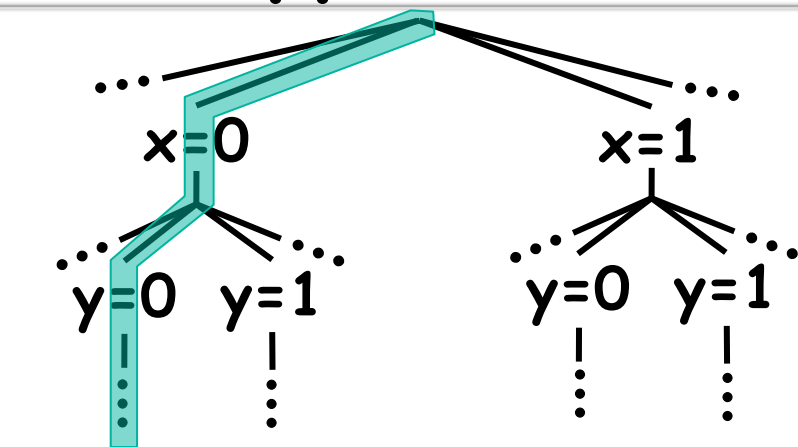
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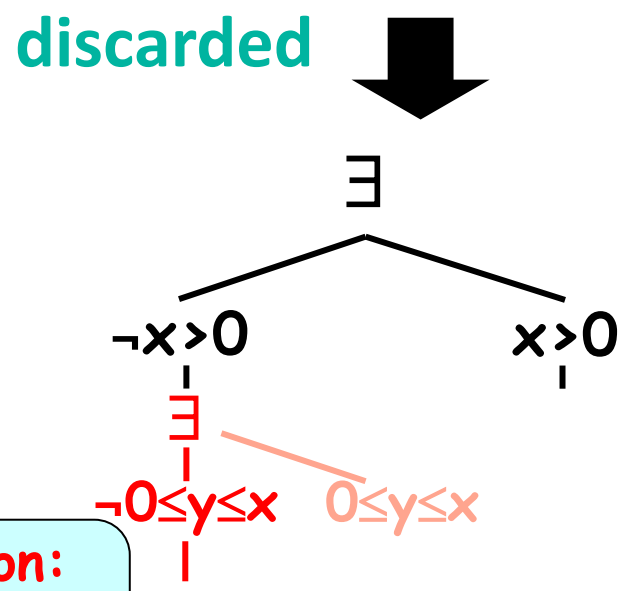
pred: $0 \leq y \leq x$



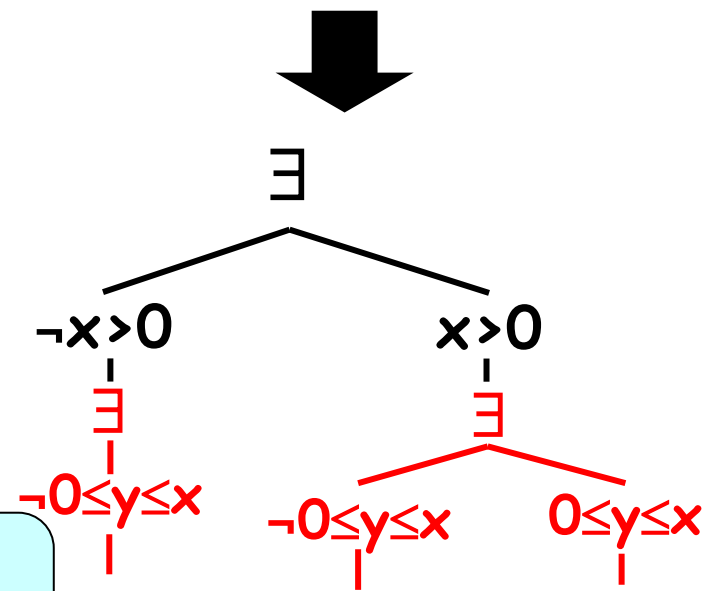
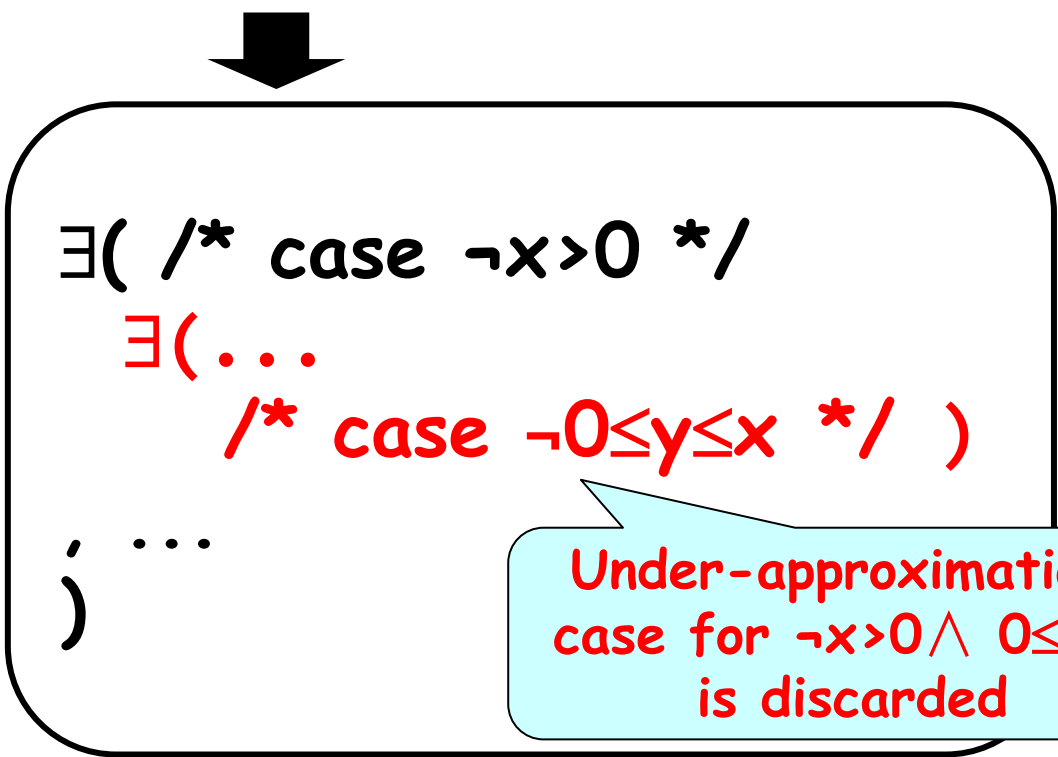
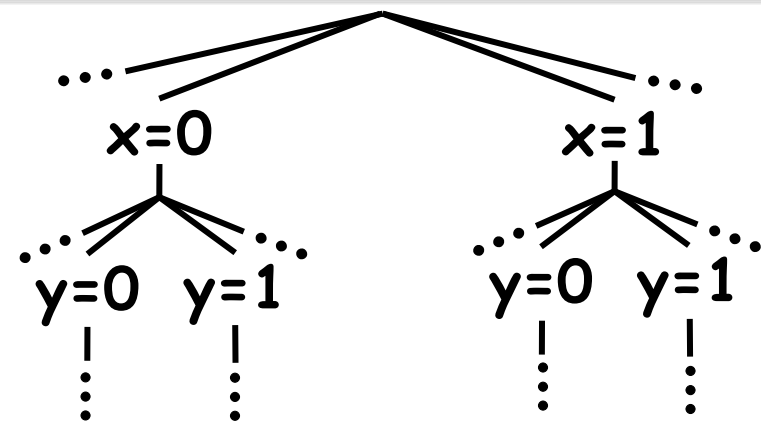
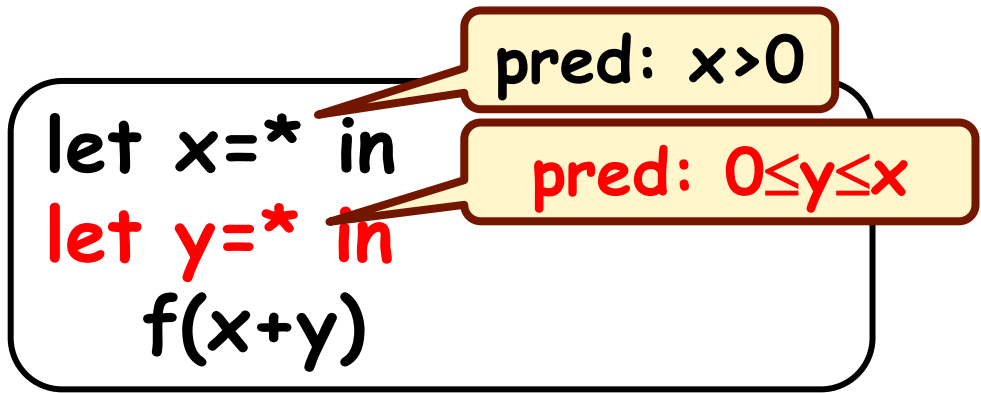
```

∃( /* case ¬x>0 */
  ∃( ...
    /* case ¬0≤y≤x */ )
  ; ...
)
    
```

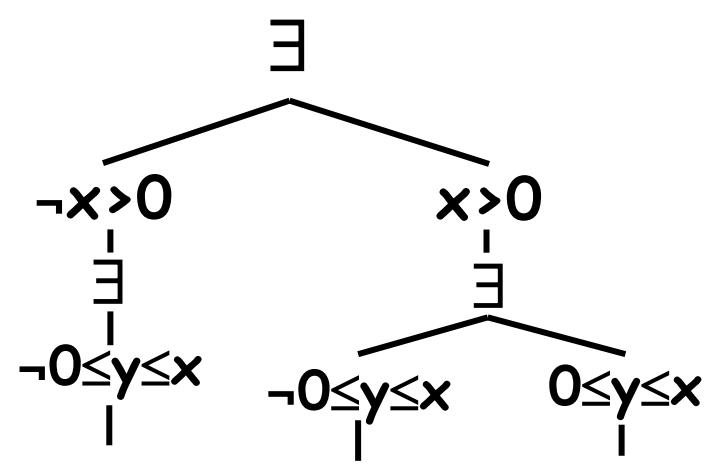
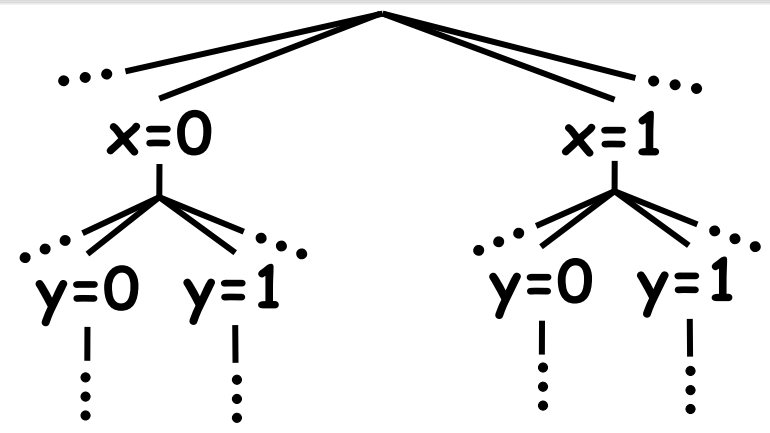
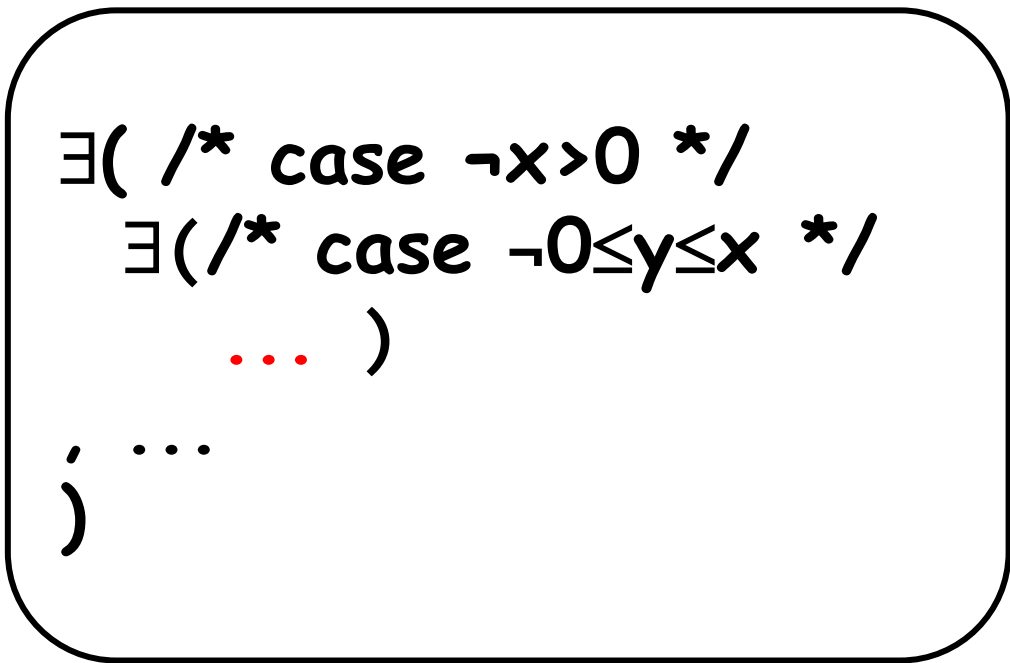
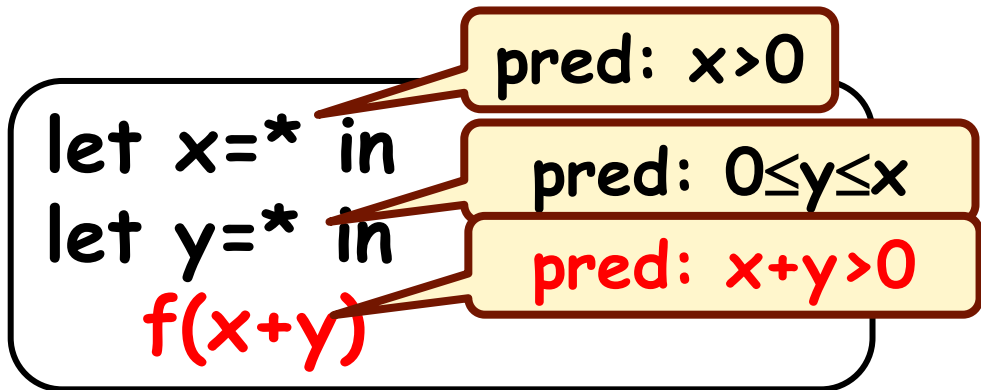
Under-approximation:
case for $\neg x > 0 \wedge 0 \leq y \leq x$
is discarded



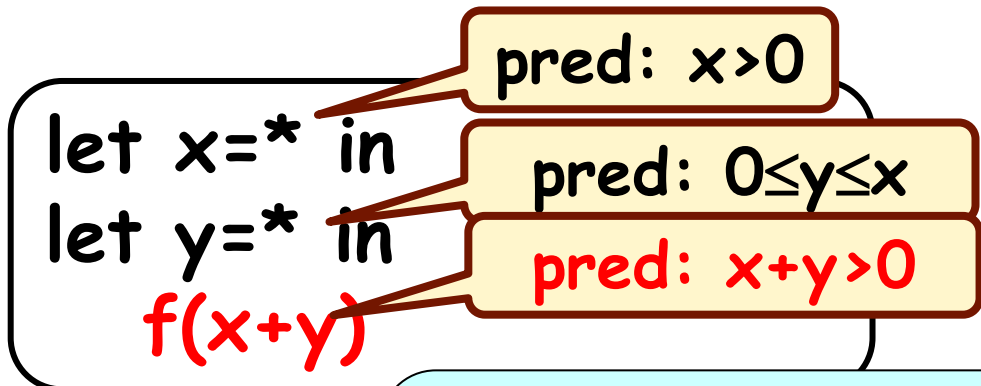
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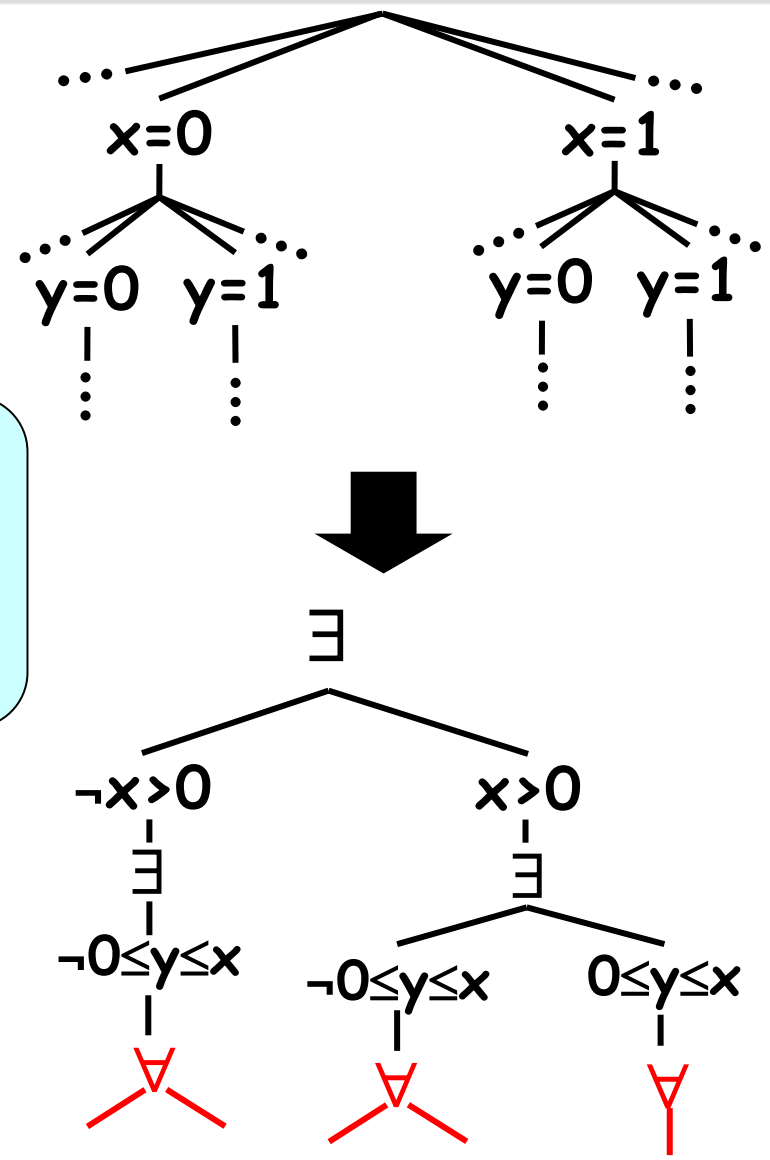
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Overapproximation:
both branches should
have an infinite path
(since we don't know
which branch is valid)

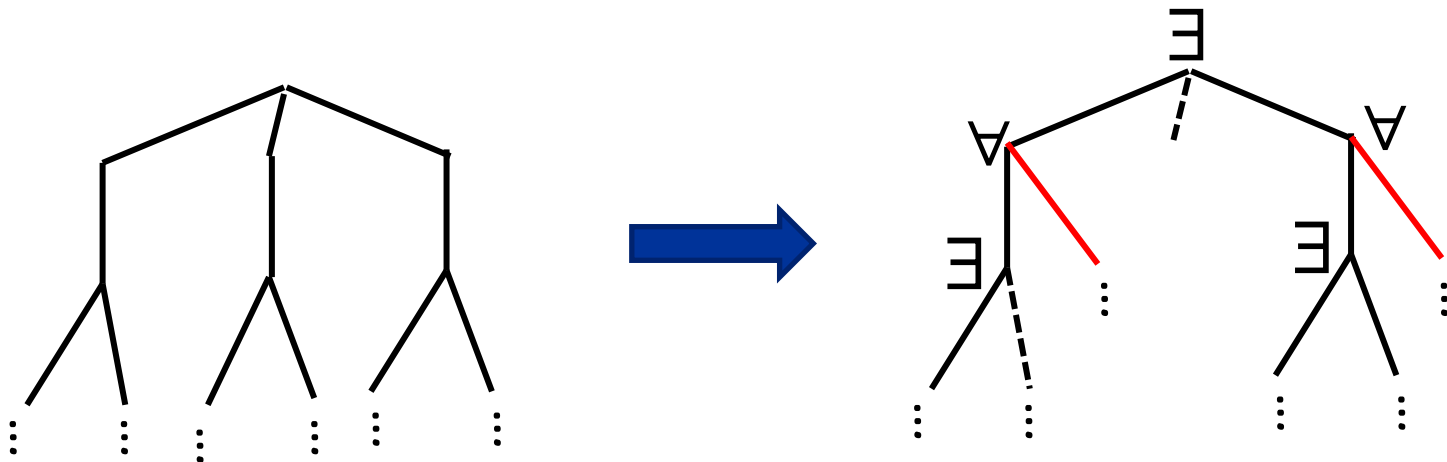
```

∃ ( /* case
  ∃ ( /* case
    ∇ ( f true /*case x+y>0 */,
      f false /*case -x+y>0 */ )
    )
  , ...
)
  
```



Non-Termination Verification: Summary

- ◆ Underapproximate non-deterministic computation, and check that **one of the branches** has a non-terminating path
- ◆ Overapproximate deterministic computation, and check that **all the branches** have non-terminating paths
- ◆ Check them by using HO model checking



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◆ Conclusion

Verification of LTL properties of HO programs

- ◆ Reduce to fair termination [Vardi 91]
- ◆ Extend the termination verification method [Kuwahara+ 14] for proving fair termination

Conclusion

- ◆ Higher-order model checking enables automated verification of functional programs
 - Various properties (including both safety and liveness properties) can be checked by an appropriate combination with abstraction and program transformation
- ◆ Do not worry too much about k-EXPTIME completeness of HO model checking
 - depending on inputs, recent HO model checkers can process inputs of thousands of lines in a few seconds