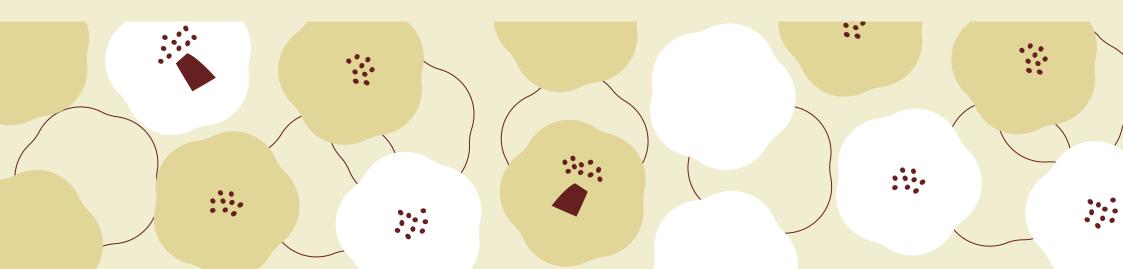


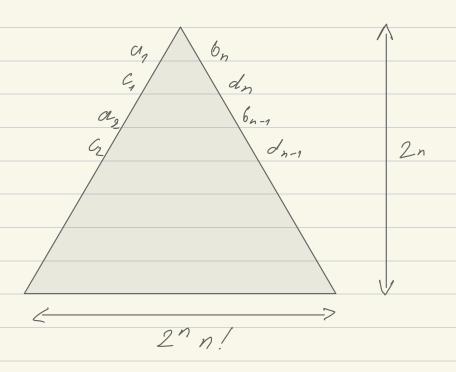
# Statefull Partial-order reduction

Igor Walukiewicz

joint work with Frederic Herbreteau, Gerald Point, and Gautham Viswanathan



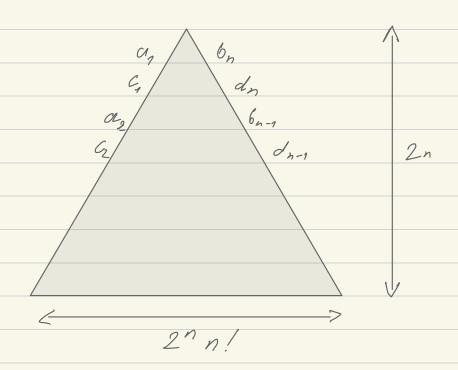


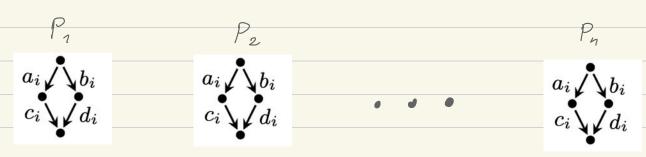




#### Small transition system



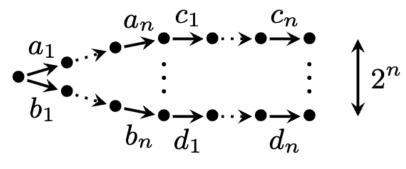




#### Small transition system



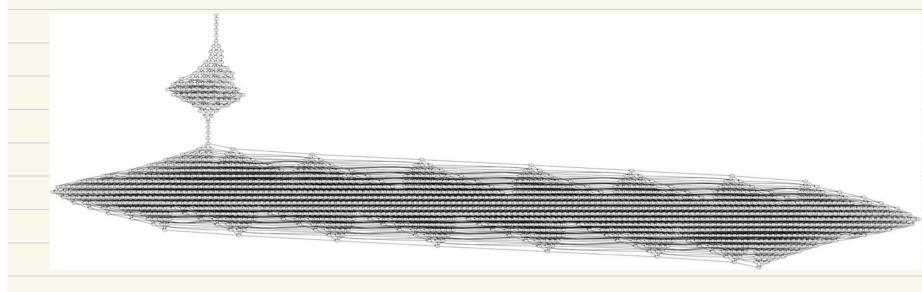
#### Big transition system





1 writer 2 readers

POR VS Reach



## Potential applications

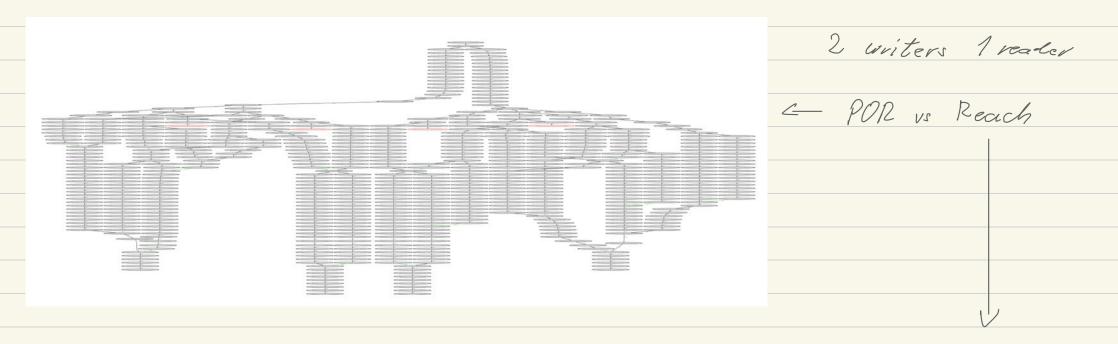
- · looking at transition systems,
- · proving correctnes,
- · verification of timed or probabilistic systems,
- " understanding parallelizm in the system.

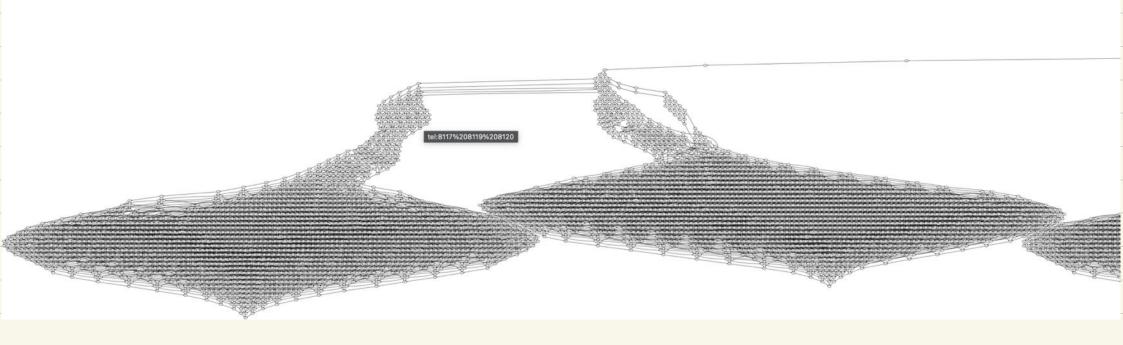
A simple correction using a lock

A more efficient correction

Sequentialization on a lock

#### TLB shootdown



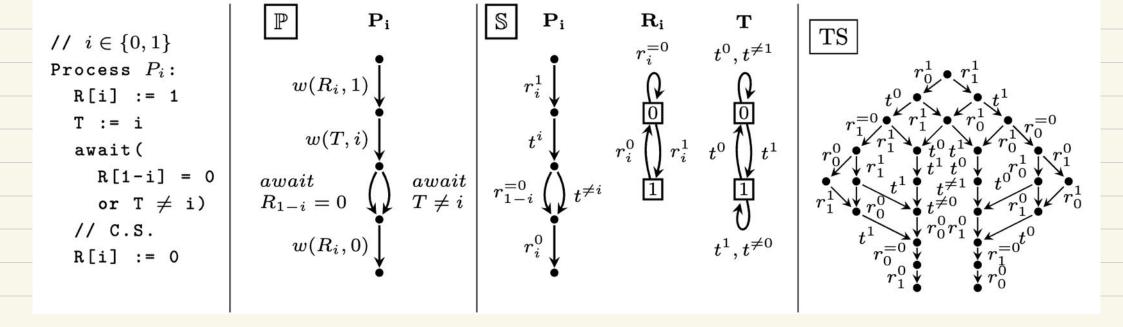


## Concurrent programs

Concurrent programs

write(x,i) await(x, I) acq(e) rel(t)

process: a DAG whose edges are labeled with actions
every process is acyclic



#### Partial-order reduction

~ - equivalence relation on sequences of actions

TS, is a reduced transition system for TS if

- · every full run of TSr is a full run of TS
- · V full run u of TJ I full run v of TS, u 2 V

Goal: construct a reduced transition system

Transition system TS
$$x := 1 \quad 0 \quad y := 1$$

$$y := 1 \quad x := 1 \quad x := 2$$

#### Partial-order reduction

~ - equivalence relation on sequences of actions

- · a(x, 10) w(y,13) a(x, 20) ~ a(x, 10) a(x, 20) w(5,13)
- · ab & ba if don (a) n don (b) = Ø

TS, is a reduced transition system for TS if

- · every full run of TS, is a full run of TS
- · Full ran u of TJ I full am v of TS, u 2 V

Goal: construct a reduced transition system

Trace optimality: TSr has the least number of full paths.

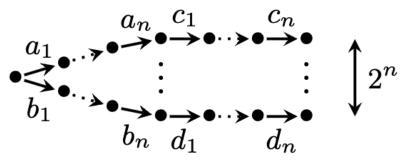
State optimality: TSv has the least number of states.

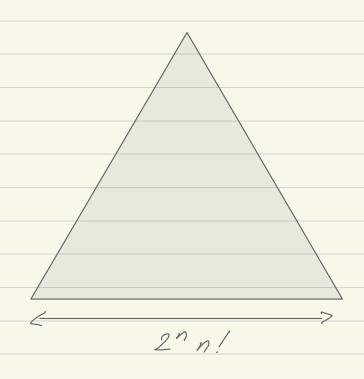


#### Small transition system



#### Big transition system

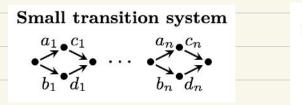


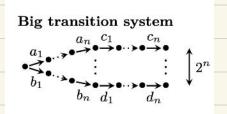


# Stateful vs Stateless POR

Stateful: store virited states, this allows to stop on revisit

Stateless: store only the current path, unique solution if states are too big





Since 2005 Flanceyon & Godeford, stateless is the mainstream 2014 Abdulla

In statefull the best we have is stubborn/persistent/ample set method

- Yang, Chen, Gopalakrishnan, Kirby "Efficient Stateful Dynamic POR"
  Model Checking Software '2008
- Civisci, Enea, Farran, Mathergil "A Pragmatic Approach to Statful POR" VMCAI 12023

- 1. POR is NP-hard
- 2. An idealized POR algorithm with IFS oracle
- 3. A heuristic for IFS oracle + implementation

#### POR is NP-hard

min TS(P): minimal size of a reduced TS for P

An excellent POR algorithm: constructs TS for Pof size  $\leq q$  (minTS(P))

in time r (1P) + minTS(P))

Thm: If I + NP then there is no excellent POR algorithm
even for programs wing only write and agait open tions.

## POR is NP-hard

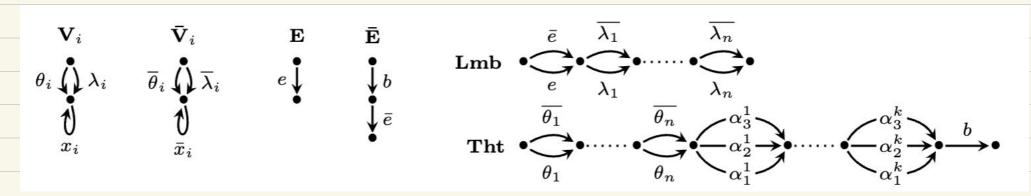
```
min TS(P): minimal size of a reduced TS for P
An excellent POR algorithm: constructs TS for P
                              of size \le q (minTS(P))
                              is time + (1) + rain TS(P))
Thm: If P+NP then there is no excellent POR algorithm
           even for programs wing only write and avait operations.
```

Proof: Use 3-SAT. For a construct Sa s.t. o 4 not SAT = min TS(See) < 6/8/ · 4 SAT => min TS (Se) > # of sat valuations of el

Consider Y = 4 n (2, v22) n... n (Z2m-, v Z2m)

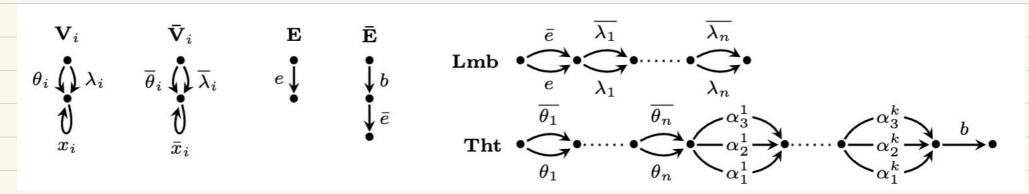
Run hypothetical Alg on Sy for r (6/41) time If it not SAT then Alg stops producing a TS for Sex If e SAT then Alg cannot stop as the smallest TS has 2">r(6/el) states

## How to construct Su



L1: If u not SAT then all runs of Su start with e, Sroof: Otherwise 6 E should appear before. For this we need a sat valuation of u

## How to construct Su



L1: If & not SAT then all runs of Se start with e.

Sroof: Otherwise 6 E should appear before.

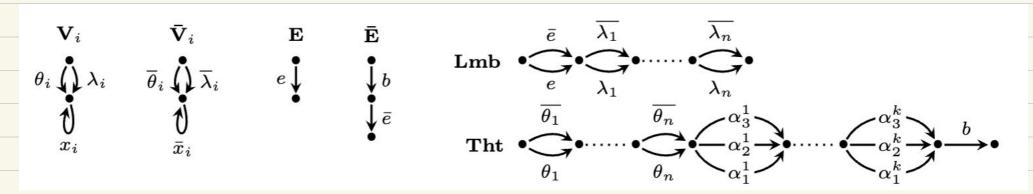
For this we need a sat valuation of a

L2 If a not SAT then the following is a good TS fra See

$$\underbrace{\stackrel{e}{\longrightarrow} \stackrel{\theta_1}{\longrightarrow} \stackrel{\overline{\lambda}_1}{\longrightarrow} \cdots \stackrel{\theta_n}{\longrightarrow} \stackrel{\overline{\lambda}_n}{\longrightarrow} \stackrel{\overline{\lambda}_n}{\longrightarrow} \stackrel{\alpha_1^1}{\longrightarrow} \cdots \stackrel{\alpha_2^k}{\longrightarrow} \stackrel{b}{\longrightarrow} \cdots \stackrel{b}{\longrightarrow} \stackrel{b}{\longrightarrow} \stackrel{b}{\longrightarrow} \cdots \stackrel{a_2^k}{\longrightarrow} \stackrel{b}{\longrightarrow} \cdots \stackrel{b}{\longrightarrow} \stackrel$$

Every run starting from e is equivalent to a run of this form

# How to construct Su



L1: If & not SAT then all runs of Se start with e.

Sroof: Otherwise 6 E should appear before.

For this we need a sat valuation of a

L2 If a not SAT then the following is a good TS fra Sa

$$\stackrel{e}{\longrightarrow} \stackrel{\theta_1}{\longrightarrow} \stackrel{\overline{\lambda}_1}{\longrightarrow} \stackrel{\overline{\lambda}_1}{\longrightarrow} \stackrel{\theta_n}{\longrightarrow} \stackrel{\overline{\lambda}_n}{\longrightarrow} \stackrel{\alpha_1^1}{\longrightarrow} \stackrel{\alpha_1^1}{\longrightarrow} \stackrel{\alpha_2^k}{\longrightarrow} \stackrel{b}{\longrightarrow} \stackrel{b}{\longrightarrow} \stackrel{a_1^k}{\longrightarrow} \stackrel{b}{\longrightarrow} \stackrel{a_1^k}{\longrightarrow} \stackrel{b}{\longrightarrow} \stackrel{a_1^k}{\longrightarrow} \stackrel{b}{\longrightarrow} \stackrel{a_1^k}{\longrightarrow} \stackrel{a_1^k}{\longrightarrow} \stackrel{b}{\longrightarrow} \stackrel{a_1^k}{\longrightarrow} \stackrel{a_1^k}{\longrightarrow} \stackrel{a_1^k}{\longrightarrow} \stackrel{b}{\longrightarrow} \stackrel{a_1^k}{\longrightarrow} \stackrel$$

Every run starting from e is equivalent to a run of this form

L3 If & SAT then there is a run starting from E for every valuation sat &.

$$\theta_1 \bar{\theta}_2 \dots \theta_n \alpha_{i_1}^1 \dots \alpha_{i_k}^k b \bar{e} \bar{\lambda}_1 \lambda_2 \dots \bar{\lambda}_n$$

- 1. POR is NP-hard
- 2. An idealized POR algorithm with IFS oracle
- 3. A heuristic for IFS oracle + implementation

#### First sets

Goal: construct a reduced transition system

First (s) = { first (u) ! u a maximal run from s}

Def Eisa source set in s if EnF # Ø for every F & Finst(s).

Prop It is enough to find Es for every s cencl explore only Es from s.

Rem Source sets are not enough even for trace optimality.

Transition system 
$$TS$$

$$x := 1 \quad 0 \quad y := 1 \quad here$$

$$y := \frac{1}{3} x := \frac{1}{4} x := 2$$

2 W(x,21) is not a source set

# Idealized algorithm, IFS oracle

```
IFS(s, B) includes first set: Is a full run first (u) = B
```

```
procedure TreeExplore(n):

Sl := sleep(n) \ / \ \text{invariant:} \ Sl = sleep(n) \cup \{ \text{labels of transitions outgoing from } n \}

while enabled(n) - Sl \neq \emptyset

choose smallest e \in (enabled(n) - Sl) w.r.t. linear ordering on actions

let s' such that s(n) \stackrel{e}{\longrightarrow} s' in TS(\mathbb{S})

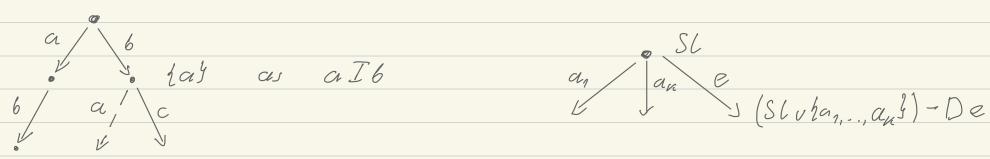
if IFS(s', enabled(s') - (Sl - De))

create node n' with s(n') = s' and sleep(n') = Sl - De

add edge n \stackrel{e}{\longrightarrow} n'

TreeExplore(n')

Sl := Sl \cup \{e\}
```



# Idealized algorithm, IFS oracle

```
IFS(s, B) includes first set: Is a full run first (u) = B
```

```
procedure TreeExplore(n):

Sl := sleep(n) \ / \ \text{invariant:} \ Sl = sleep(n) \cup \{ \text{labels of transitions outgoing from } n \}

while enabled(n) - Sl \neq \emptyset

choose smallest e \in (enabled(n) - Sl) w.r.t. linear ordering on actions

let s' such that s(n) \stackrel{e}{\longrightarrow} s' in TS(\mathbb{S})

if IFS(s', enabled(s') - (Sl - De))

create node n' with s(n') = s' and sleep(n') = Sl - De

add edge n \stackrel{e}{\longrightarrow} n'

TreeExplore(n')

Sl := Sl \cup \{e\}
```

Fact: This algorithm constructs a trace optimal tree

 $a_n$   $a_n$  e  $(Slvha_{n-1},a_n\beta)-De$ 

Fact: IFS (s, B) test is
NP-hard.

- 1. POR is NP-hard
- 2. An idealized POR algorithm with IFS oracle
- 3. A heuristic for IFS oracle + implementation

## A heuristic for IFS(s, B)

Concurrent programs

write(x,i) read(x, I) acq(l) rel(l)

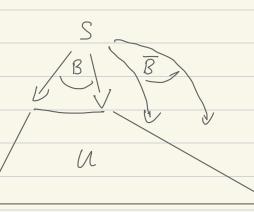
every process is acyclic

Equivalence

 $u \sim V$ 

finit (a) = 26: 76v 2 a 3

1FS (s, B)



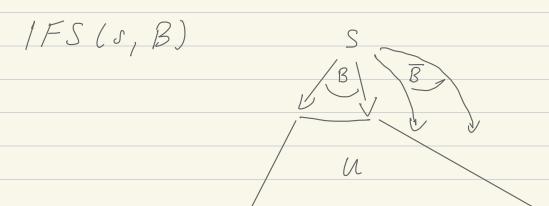
first (a) & B

YagB Jbagu

 $a D b_a$ 

 $\alpha_{1}(x,5)$  D  $\omega_{1}(x,6)$  $\omega_{1}(x,1)$  D  $\alpha_{1}(x,0)$   $\in$  initial read

# A heuristic for IFS



first (a) & B

tag B J ba Gu

a D ba

1) 
$$\omega(x,1) \in APW_{S,B}$$
  
2)  $\omega(x,2) \in APW_{S,B}$   
3)  $\omega(y,3) \in APW_{S,3}$ 

so IFS (s, B) holds

## Computing AIR, APW

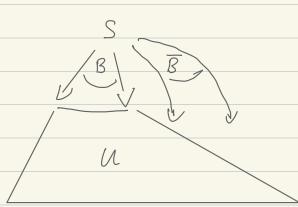
Rem: This is only an approximation

$$\begin{bmatrix}
p' & q & r \\
& \omega(x,0) \downarrow & q & \alpha(x,0) \downarrow & \omega(y,4) \downarrow & We & still yet & \omega(y,3) \in APW_{S,B} \\
& \alpha(x,2) \downarrow & \omega(x,2) \downarrow & \omega(x,2) \downarrow & but & this, & time & it is wrong. \\
& \alpha(x,2) \downarrow & \omega(y,3) \downarrow$$

$$\omega(y,3) \downarrow$$

# A heuristic for IFS(s, B)

1FS (s, B)



first (a) E B

YagB Jbagu

a D ba

 $a_p(x, 5) D w_q(x, 6)$   $w_p(x, 1) D r_q(x, 0) \leftarrow initial read$ 

We want to compate:

(A/R, APW) = \( \lambda \lambd

Signatures

Sig 
$$(a_p(x,0) \ \omega_p(x,1)) = ( \frac{1}{2} a(x,0) \frac{1}{2}, \emptyset, \{ \omega(x,1) \frac{1}{2} \})$$
  
Sig  $(\omega_p(x,1) \ a_p(x,2)) = ( \emptyset, \{ a(x,2) \}, \{ \omega(x,1) \})$ 

We will precompute Sigsp(Sp,b) for every process p and  $Sp^{-1}$  in p  $Sigsp(Sp,b) = SSig(a) : Sp^{-6} - \frac{a}{3} a ran$ 

$$//\ i \in \{0,1\}$$
Process  $P_i$ :

R[i] := 1

T := i

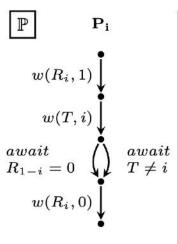
await(

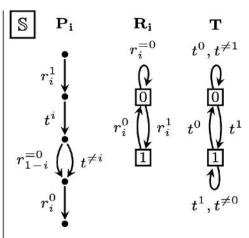
R[1-i] = 0

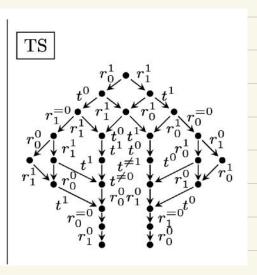
or T  $\neq$  i)

// C.S.

R[i] := 0







# Our approach

- 1) Do pre-processing: fully explore each process to compute signatures
- 2) At each state do poly (1P1) work to compute required PIFSIS, B)
- 3) Do not traverse constructed TS more than DFS does

TS grows exponentially art to 191 while we can hope to keep poly (111) small

Rem 1: PIFS (s, B) is sometimes strictly stronger than persistent sets.

Rem 2: We use some I weak) contextual independence relation.

# Experiments

[X f - 1 - 1 - 1			Г						02	1 . 0		
Models	opifs N time		pifs N Tr time			p-sets		spin		ic3	bdd	
11 0	10 00 000	time	the same control of the same o	Tr	time	N	time	N	time	time	time	
bk, 3	1.4 k	0.0	3.6 k	557.0	0.0	10.7 k	0.0	11.7 k	0.0	TO TO	TO TO	
bk, 4	86.4 k	15.8	197.1 k	1.6e+05	26.5	1.7 M	28.4	1.7 M	1.3			
bk-lt, 3	331	0.0	912	85.0	0.0	2.7 k	0.0	3.0 k	0.0	272.0	637.4	
bk-lt, 4	6.2 k	0.3		2.6e+03	0.4	129.0 k	1.4	118.6 k	0.1	TO TO	TO	
bk-lt, 5	159.1 k	50.1	406.5 K	1.5e+05	91.8	9.2 M	171.6	7.0 M	$7.2 \\ 1350.0$	27,337	TO	
bk-lt, 6		TO		TO		TO				TO	TO	
bk-b, 3	632	0.0	1.7 k	281.0	0.0	4.8 k	0.0	4.6 k	0.0	8.9	288.4	
bk-b, 4	17.9 k	$\frac{1.1}{305.4}$	49.2 k 1.8 M	2.4e+04	1.6 596.6	357.3 k	$3.8 \\ 945.9$	284.2 k	0.4 86.9	TO TO	TO TO	
bk-b, 5	650.2 k 277	0.0		5.3e+06 95.0	0.0	42.9 M 2.8 k	0.0	27.3 M 3.0 k	0.0	9.3	710.3	
	545, 157, 557	100	803		750 155.00	CHARLES THE COLUMN	75 5550	Fig. 400 (1525) (60)	0.000 90	TO TO	25.000000	
bk-ba, 4	4.2 k 74.2 k	0.2	11.4 k		0.3	152.7 k	$\frac{1.6}{271.0}$	141.2 k	$0.1 \\ 23.9$	TO	TO TO	
bk-ba, 5		28.7 0.9	197.8 k		58.2	14.4 M		11.2 M			TO	
dp-o, 20	8.1 k	107777333	29.1 k	1e+06	1.1	3554	7,00		92	9.8	TO	
dp-o, 29	33.0 k	6.9	119.6 k	5.4e + 08	7.8	TO		TO		10/11/01/25	(2000)	
dp-o, 30	37.9 k 276.2 k	$7.9 \\ 149.2$	135.8 k 986.2 k	1.1e+09	$8.9 \\ 154.2$	TO TO		TO TO		TO TO	TO TO	
dp-o, 50 dp-b, 11	256.6 k	20.9	724.1 k	1.1e+15	25.2	TO		TO		10.6	TO	
dp-b, 13	1.3 M	146.4		4.8e+06 7.7e+07	170.8	T	×2	TO	55	6.6	TO	
2000 B2000 B00000 F	6.2 M	913.6	200 N = 0 V D 200 E C 100 E C	1.2e+09	1151.3	T		TC		8.3	TO	
dp-b, 15 dp-ao, 16	33.9 k	3.9		1.7e+07	4.0	TO	22	TO		TO	TO	
dp-ao, 30	473.5 k	149.5		3.6e+13	139.4	T		TC		TO	TO	
lz, 12	16.4 k	0.5	36.8 k		0.7	11.8 M	298.6	16.1 M	41.1	23.0	TO	
lz, 12	32.7 k	1.1	73.7 k	1.5e+04 3.3e+04	1.6	43.9 M		59.9 M	195.0	200.8	TO	
lz, 13	65.5 k	2.5	147.4 k	7e+04	3.5	T(		223.6 M		149.9	TO	
lz, 16	262.1 k	11.1	589.7 k	3.1e+05	16.2	T		TC		TO	TO	
lz, 18	1.0 M	50.4	2.4 M		72.7	TO		TO		320.6	TO	
lz, 20	4.2 M	230.8	9.4 M	6e+06	368.5	TO	25	TC		TO	TO	
lz, 22	100000000000000000000000000000000000000	1330.8	37.7 M	2.6e+07	1948.0	TO		TO		TO	TO	
pet, 3	41	0.0	124	32.0	0.0	210	0.0	276	0.0	13.5	7.6	
pet, 4	630	0.0	1.7 k		0.0	3.4 k	0.0	4.5 k	0.0	TO	TO	
pet, 5	15.5 k	1.2	39.3 k	3.9e+06	1.3	106.1 k	1.4	129.6 k	0.2	TO	TO	
pet, 6	633.6 k	150.2	1.5 M		182.6	5.4 M	107.2	5.8 M	22.2	TO	то	
pet, 7	T	THE RESERVE THE PROPERTY OF		ТО		T	The second control of the second	371.8 M	1090.0	TO	ТО	
rcu, 7	26.4 k	2.1	93.1 k	7.8e + 04	2.9	76.1 M	2115.2	55.4 M	147.0	2.9	2307.1	
rcu, 8	100.8 k	9.7	355.7 k		14.1	T		602.5 M	2090.0	3.7	TO	
rcu, 9	388.1 k	48.7	1.4 M	2e+06	74.0	TO	о	TC		13.5	TO	
szy, 4	3.1 k	0.1	9.0 k	1.1e+05	0.1	34.5 k	0.2	29.1 k	0.0	1605.8	323.3	
szy, 5	41.4 k	2.6	112.1 k	1.3e + 08	3.3	868.5 k	9.0	603.1 k	1.1	TO	TO	
szy, 6	620.9 k	69.0	1.6 M	1.6e+12	93.8	25.1 M	416.1	14.1 M	42.8	TO	TO	
szy, 7	T	0		TO		T	О	365.9 M	762.0	TO	TO	
tlb, 2, 1	125	0.0	552	24.0	0.0	12.9 k	0.1	14.1 k	0.0	ТО	ТО	
tlb, 2, 2	607	0.0	2.6 k	160.0	0.0	307.4 k	4.3	327.9 k	0.9	TO	TO	
tlb, 3, 1	13.6 k	1.1	58.0 k	2.8e+04	1.5	2.7 M	45.9	1.7 M	5.7	TO	ТО	
tlb, 3, 2	173.6 k	19.8	745.5 k	1.8e+06	25.8	T	Э	52.0 M	177.0	TO	ТО	
tlb, 4, 1	2.3 M	330.4	9.6 M	3e+08	425.8	TO	о	183.2 M	618.0	TO	ТО	
token, 3	990	0.0	2.0 k	3.9e + 04	0.0	20.6 k	0.1	21.1 k	0.0	16.6	250.5	
token, 4	31.9 k	1.3	65.6 k	1.7e + 15	1.5	1.5 M	18.0	1.5 M	1.9	TO	ТО	
token, 5	589.6 k	34.0		1.9e + 18	39.0	64.5 M	1562.7	62.9 M	150.0	TO	TO	
token, 6	8.1 M	700.3	17.1 M	1.6e + 19	806.5	T	)C	TC	)	TO	ТО	

19	
57	bakery
66	
189	
	dinning philosophers
	last zero
8,5	peterson
	read-copy-update
40	Szymański
40	
79	TLB cache coherence
108	demand driven

token-ving

#### Conclusions

- · POR is computationally difficult, so we need heuristics.
- « We do not have a convienient rucce» measure (state optimality)
- · Our heuristic is quite satisfactory for variable, and locks.

#### TODO

- 1) Handling cycles
- 2) Symmetry reduction.
- 3) Weak memory models
- 4) PIFS for other constructs (channels, ...).